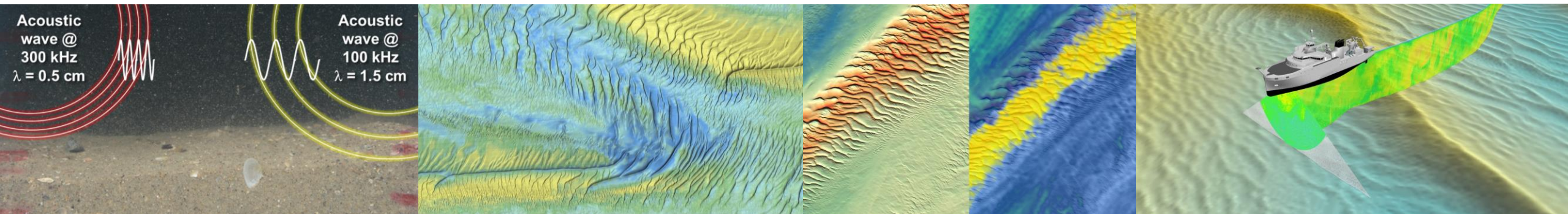
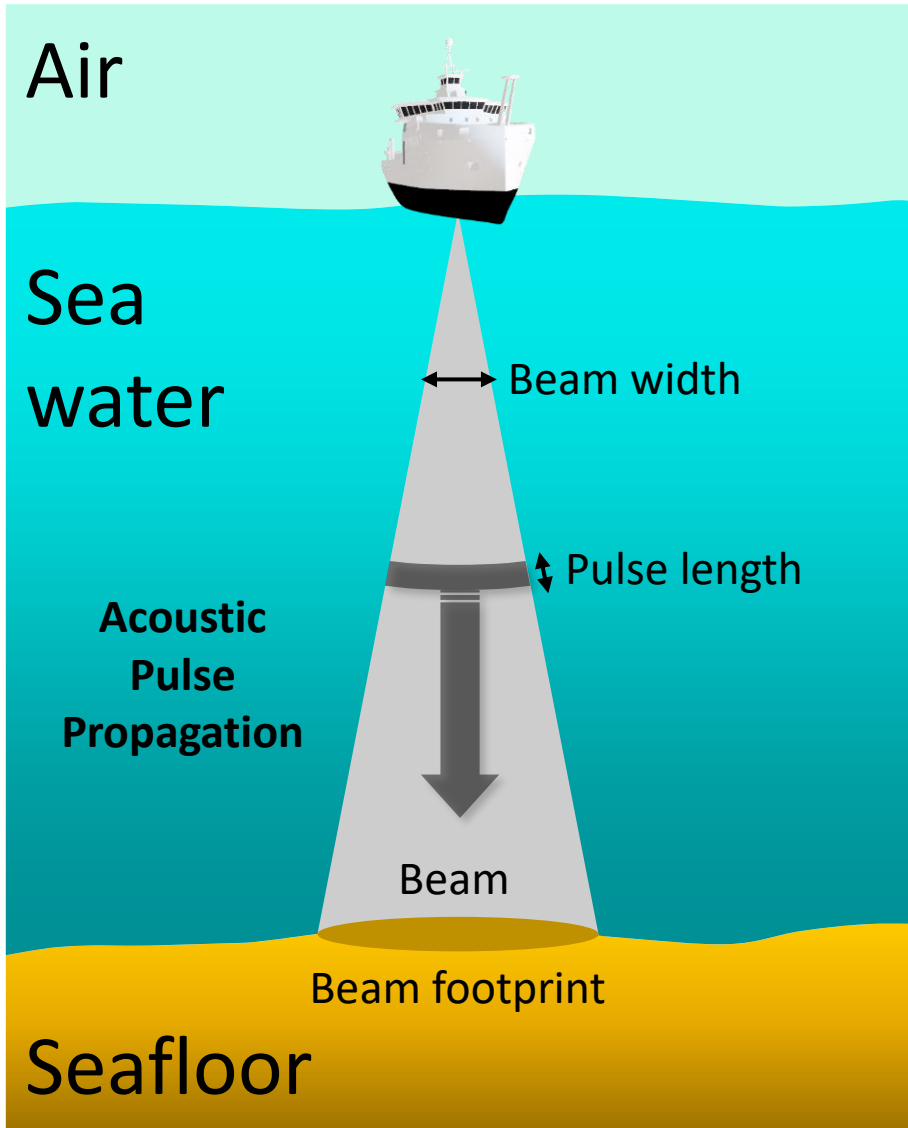


Unveiling the Wonders of Backscatter

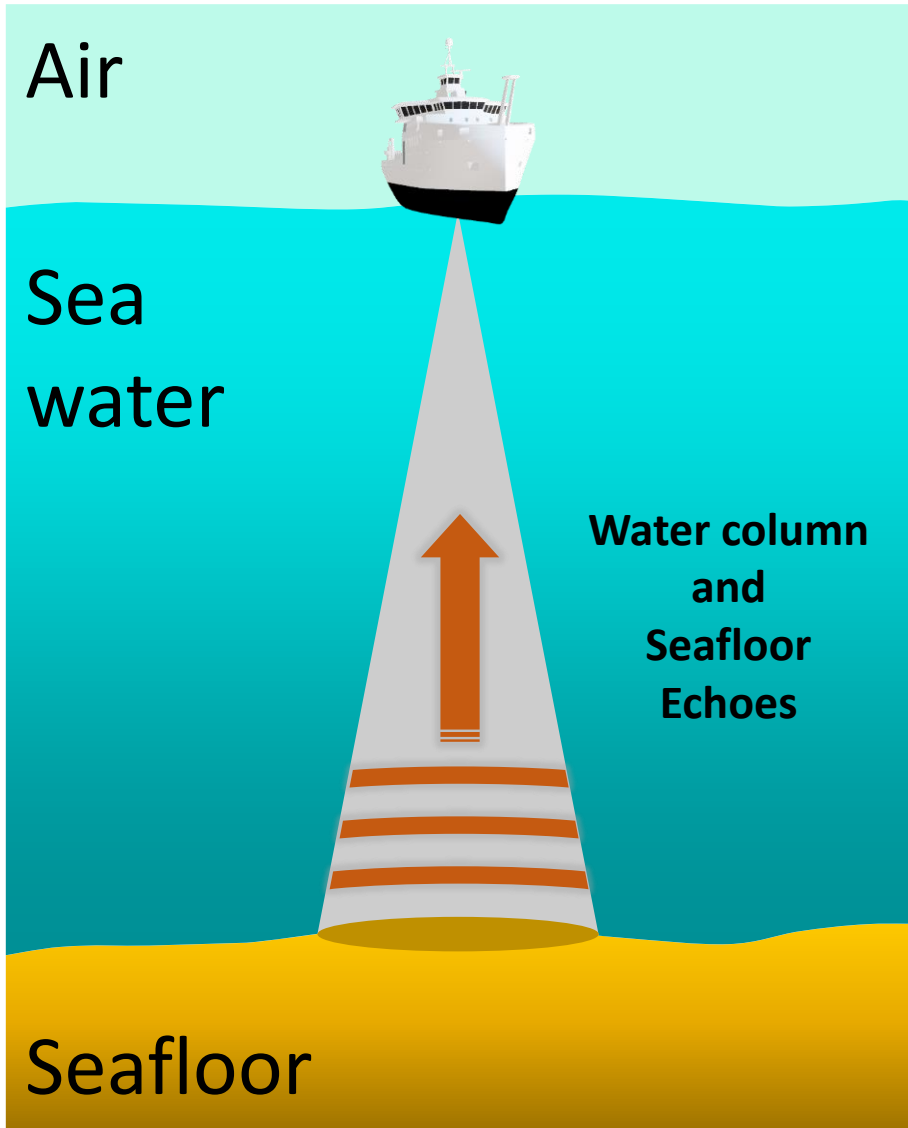


Marc Roche
Study Day 2024

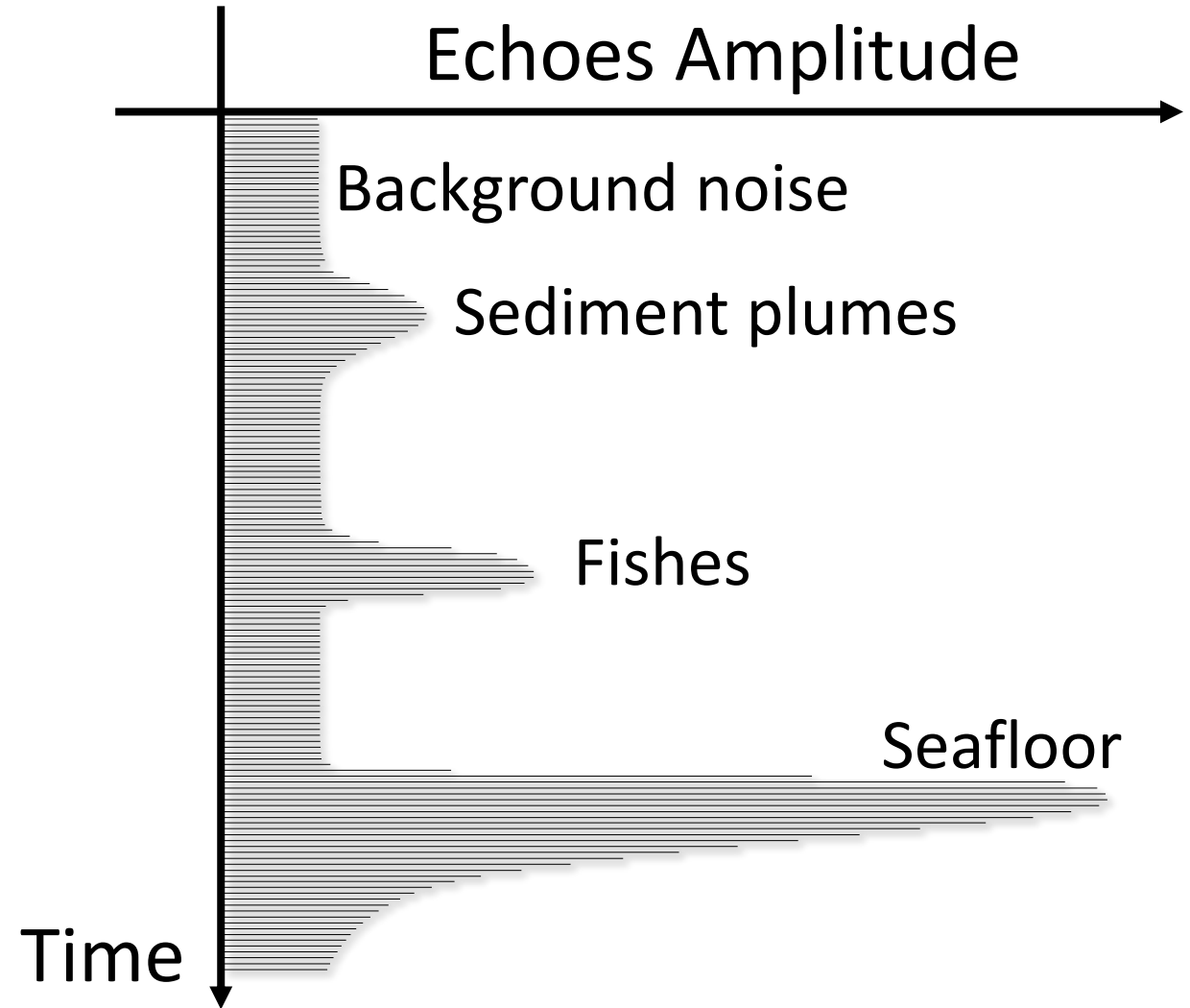
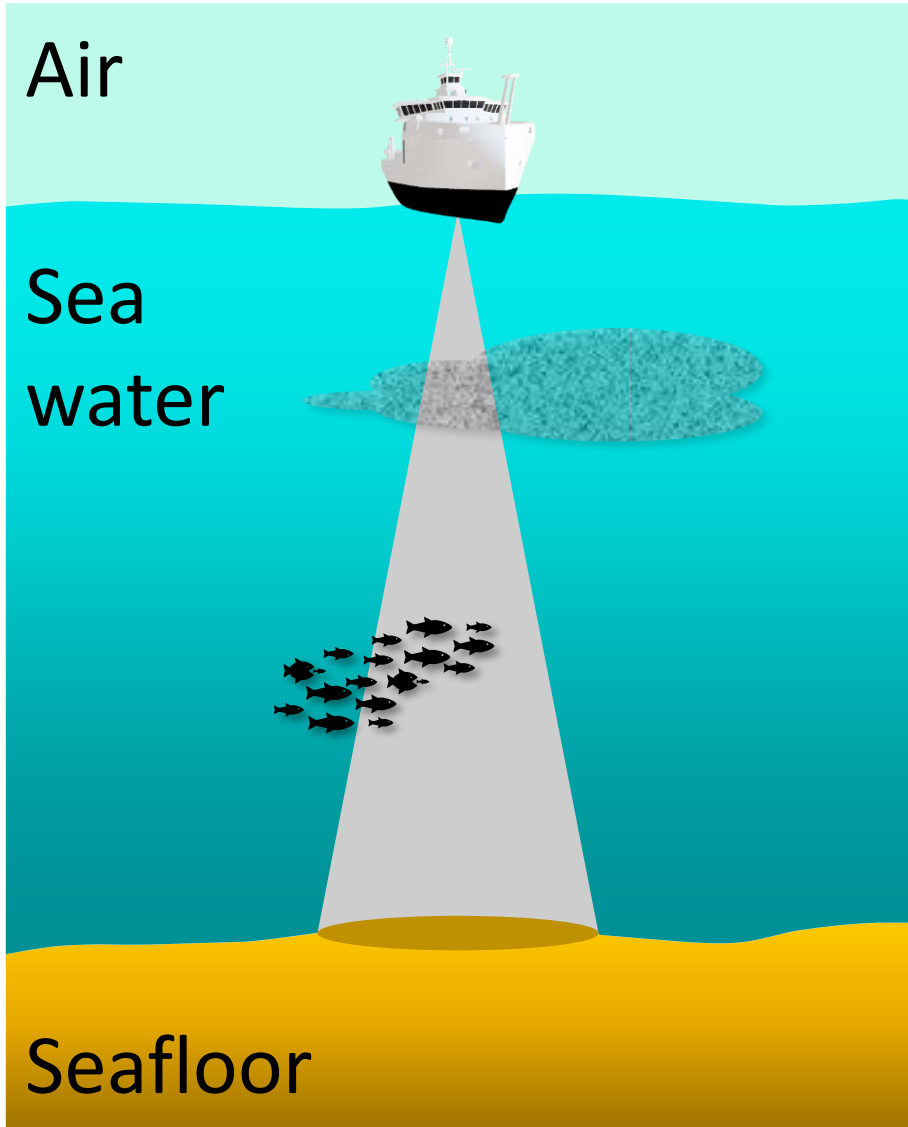
What are we talking about?



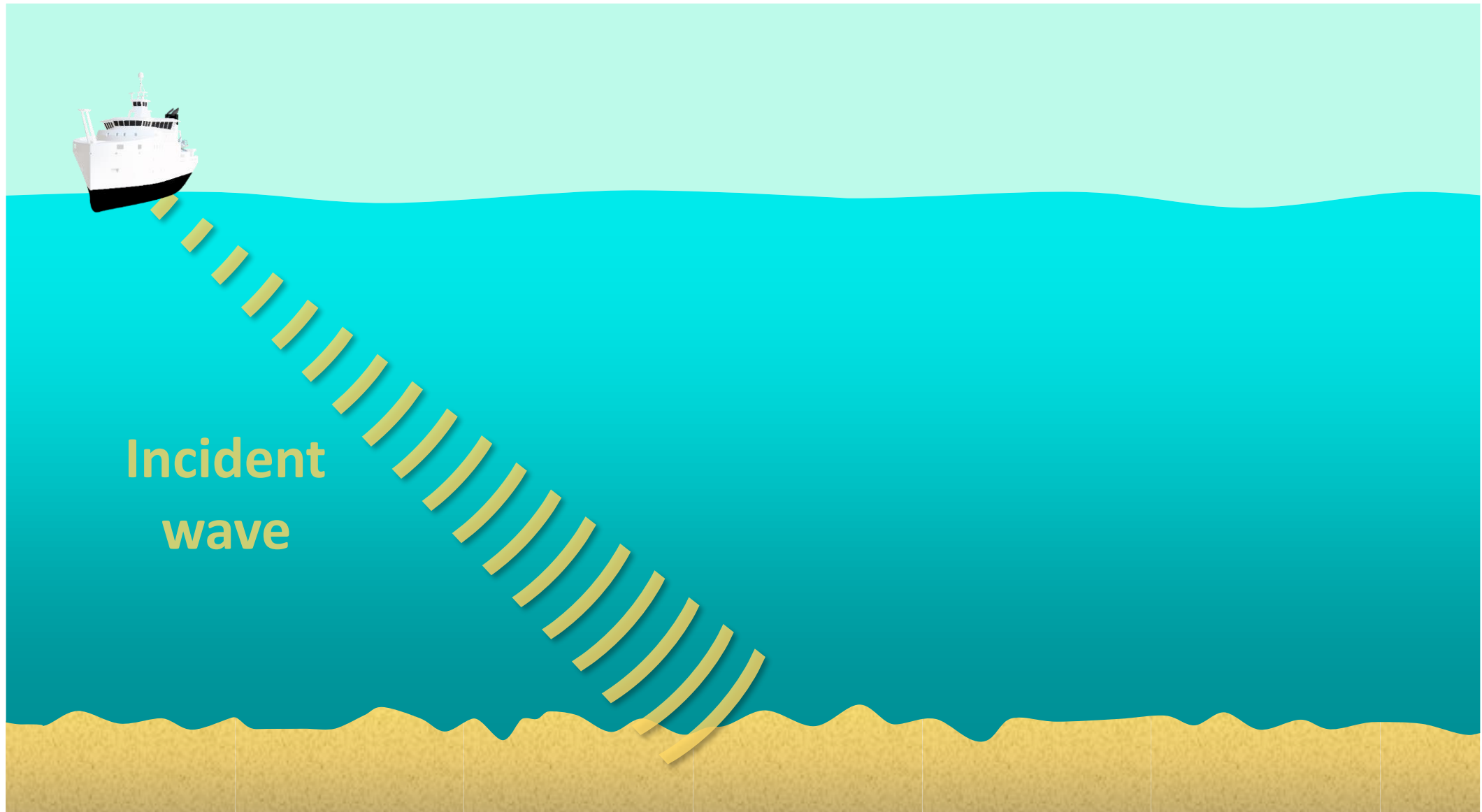
What are we talking about?



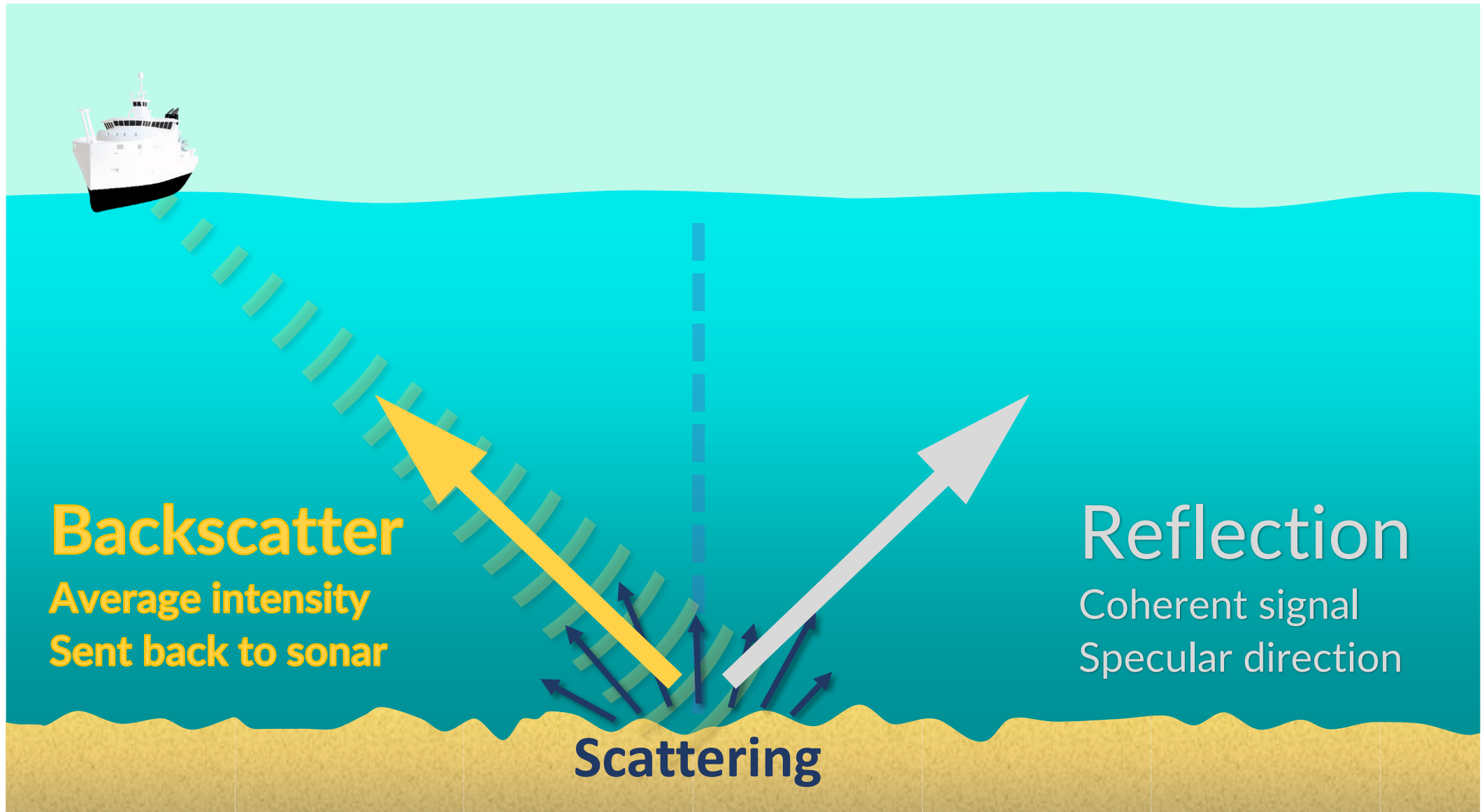
What are we talking about?



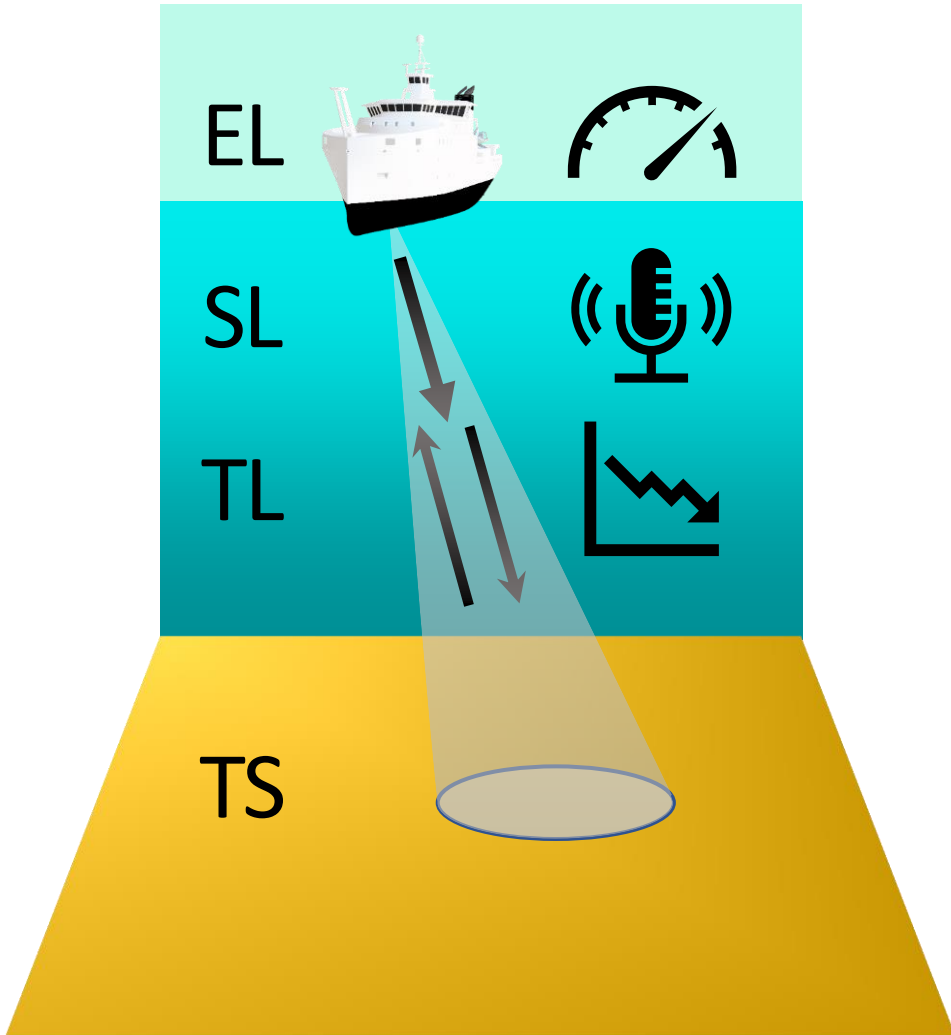
Terminology



Terminology



The Sonar Equation (in dB): $EL = SL - 2 TL + TS$



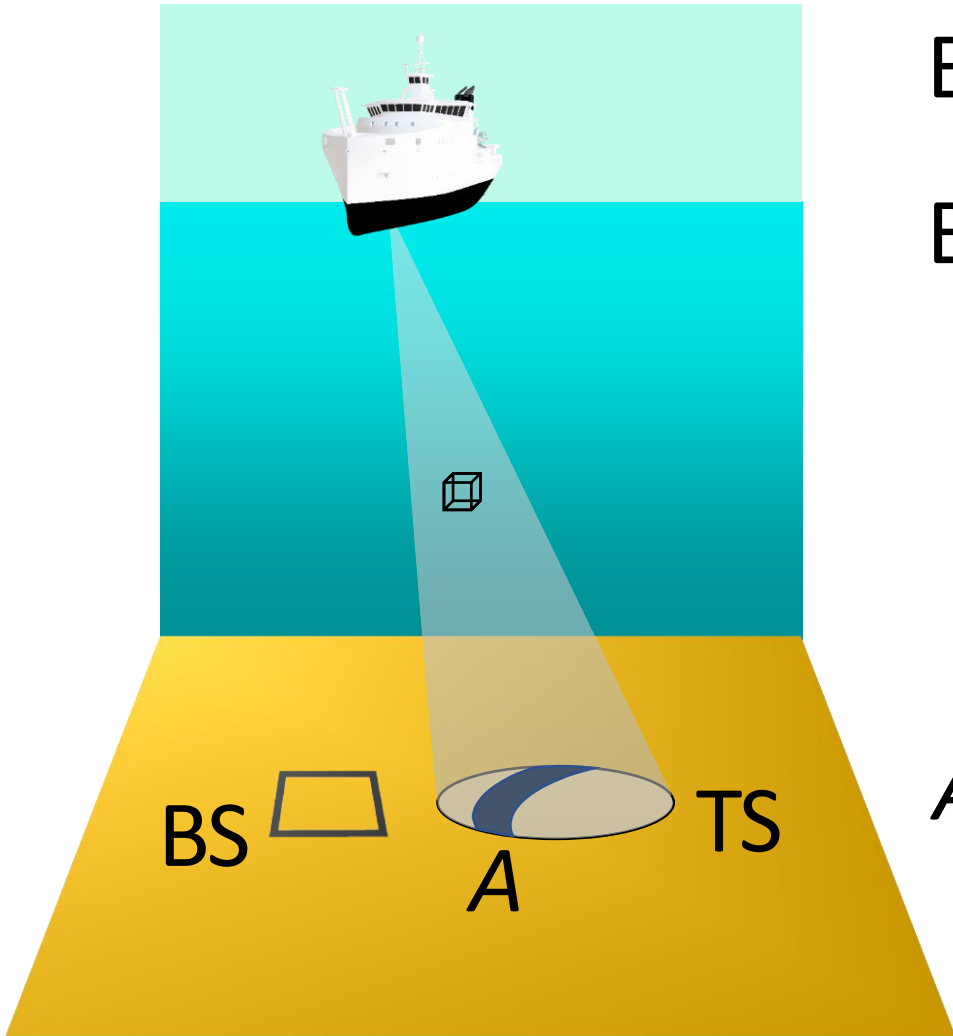
EL = Echo Level

SL = Source Level

TL = Transmission loss

TS = Target Strength = $\frac{\text{Backscatter intensity}}{\text{Incident intensity}}$

Backscatter Strength - BS



$$BS = TS - 10 \log A$$

BS = Backscatter Strength (dB)

Target Strength (dB) of 1 m² seafloor

- Seafloor type & characteristics
- Incident angle
- Frequency

A = Instantaneous ensonified area (m²)

- Sonar aperture ; signal duration
- Sonar configuration (range, angle...)

In Water Column: Sv = Volume Backscattering Strength (dB/m³)

Backscatter Strength - BS - dB

$$\text{BS in dB} \sim \log_{10} \left\{ \frac{\text{backscatter intensity}}{\text{Incident intensity}} \right\}$$

Negative values:
backscatter intensity < incident intensity

Indicative values

Sediment Type	Typical BS (dB)
Mud - Silt	-30 dB to -20 dB
Fine - Medium sand	-20 dB to -15 dB
Medium - Coarse sand	-15 dB to -10 dB
Coarse sand - Gravel	-10 dB to -5 dB
Gravel	-5 dB to 0 dB

dB is not a linear scale!

Δ dB	Equivalent x Intensity
1	1.3
2	1.6
3	2.0
4	2.5
5	3.2
10	10
20	100
30	1000

Coarse sand (-15 dB) generates an echo 100 times more intense than a Silt (-25 dB)!

The Quest for the Holy Grail

Impedance
Roughness
Volume

Seafloor type and characteristics

Sonar aperture
Pulse length
Measurement range
Measurement angle
Seafloor bathy-morphology

Frequency
Incident angle
Insonified area

Seawater temperature
Seawater salinity
Depth
Suspended Particulate Matter

Attenuation - absorption

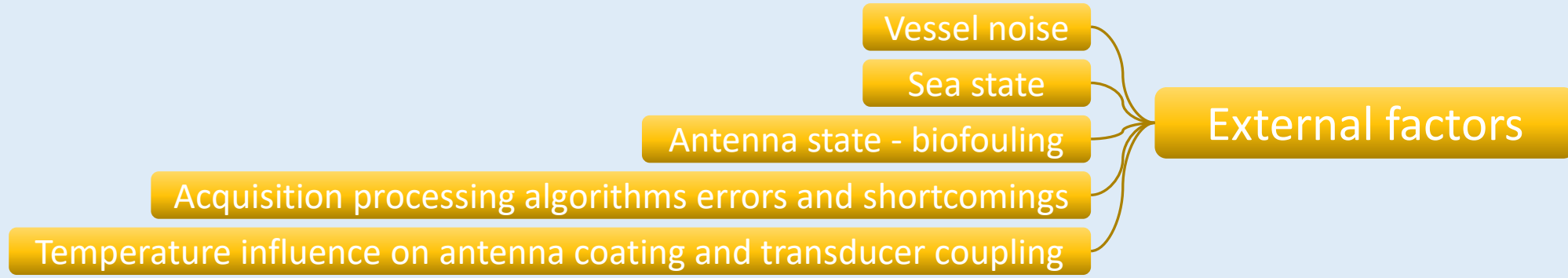
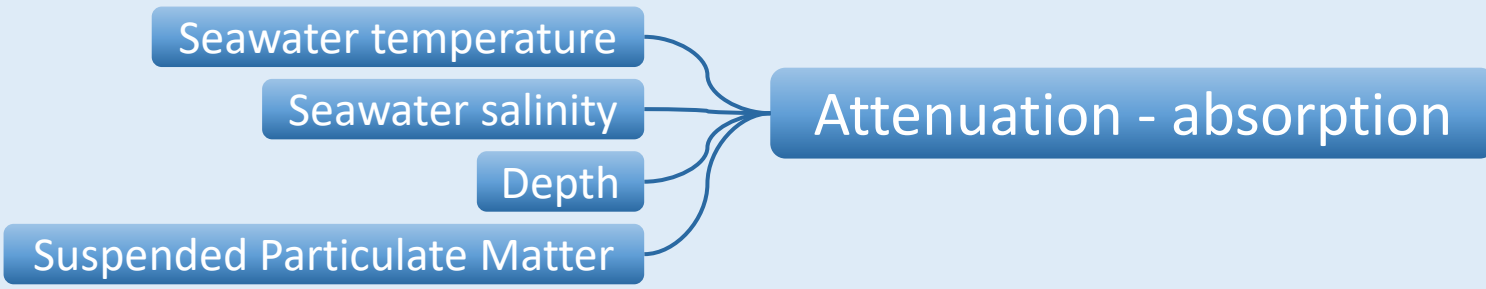
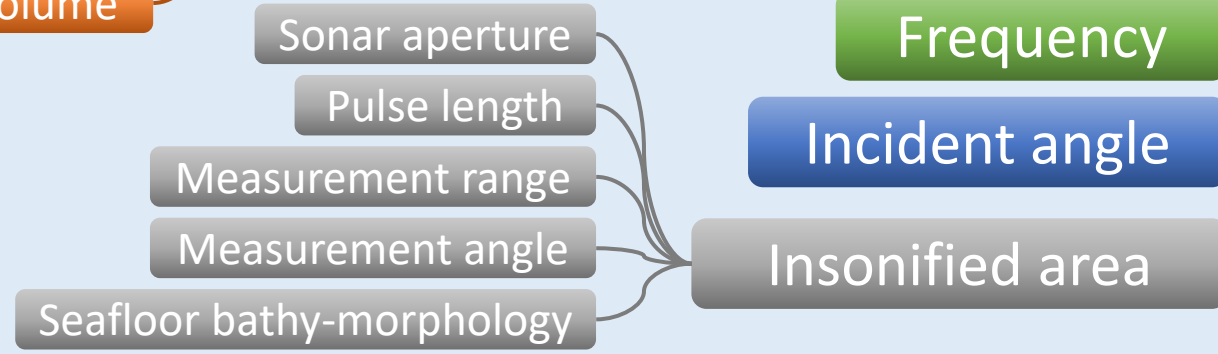
Vessel noise
Sea state
Antenna state - biofouling
Acquisition processing algorithms errors and shortcomings
Temperature influence on antenna coating and transducer coupling

External factors

Calibration

BS

The Quest for the Holy Grail



Frequency

Incident angle

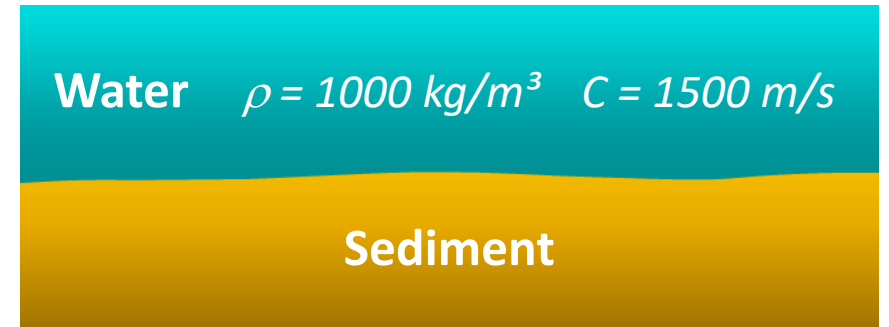
BS

Acoustic impedance

- Acoustic impedance = $Z = \rho \cdot c$

ρ = density kg/m³

c = acoustic velocity m/s

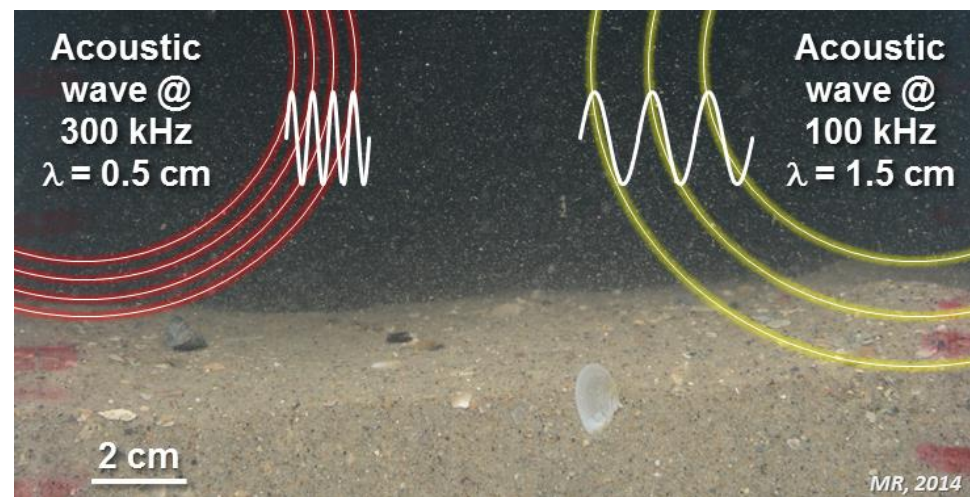


- Impedance contrast sediment – water = $V = \frac{Z_{\text{water}} - Z_{\text{sed}}}{Z_{\text{water}} + Z_{\text{sed}}}$

	ρ kg/m ³	C m/s	Z_{sed}	V	V dB
Clay	1200	1470	$1.76 \cdot 10^6$	0.081	-21,8
Clayey silt	1500	1515	$2.27 \cdot 10^6$	0.204	-13,8
Sand + silt	1700	1600	$2.72 \cdot 10^6$	0.290	-10,7
Coarse sand	2000	1800	$3.60 \cdot 10^6$	0.411	-7,7

Roughness and Frequency

- Roughness is the ratio of average micro-relief to wavelength $\lambda (= \frac{V}{F})$
- Relative notion:

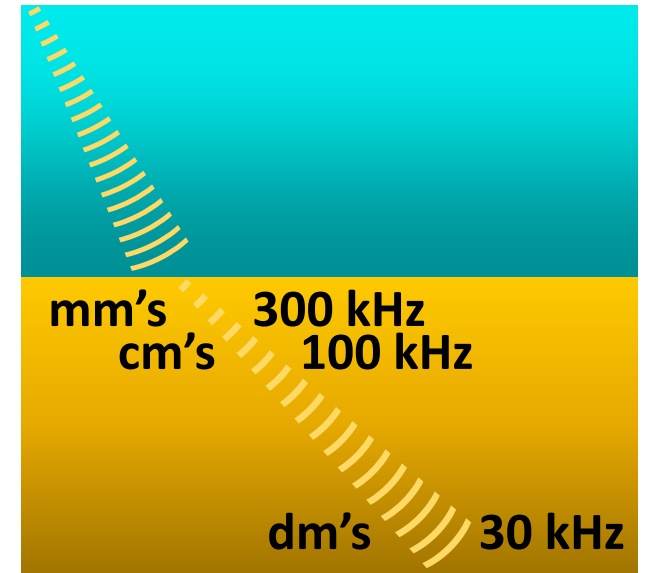
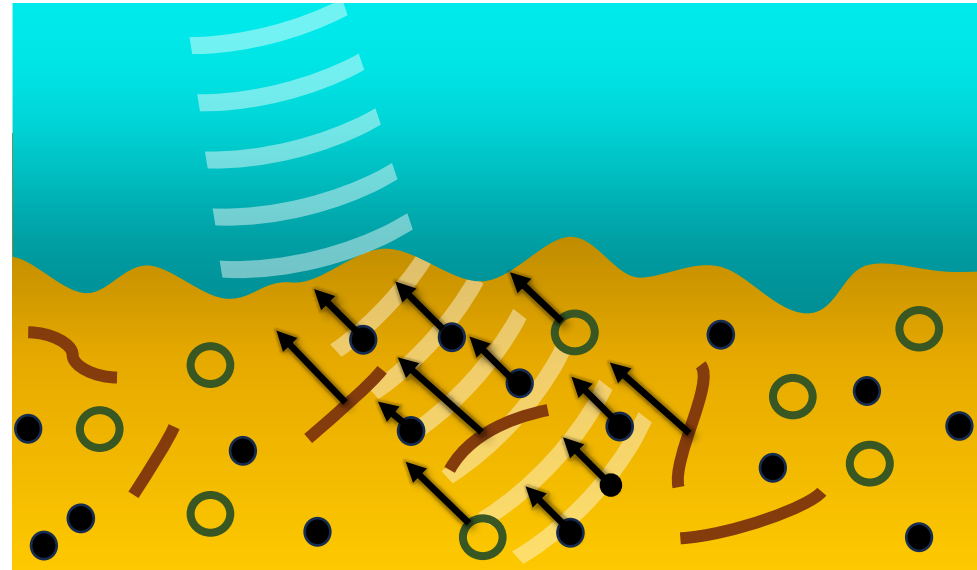


- The rougher the sediment interface, higher the backscatter
- Roughness strongly correlated with sediment impedance

Volume contribution

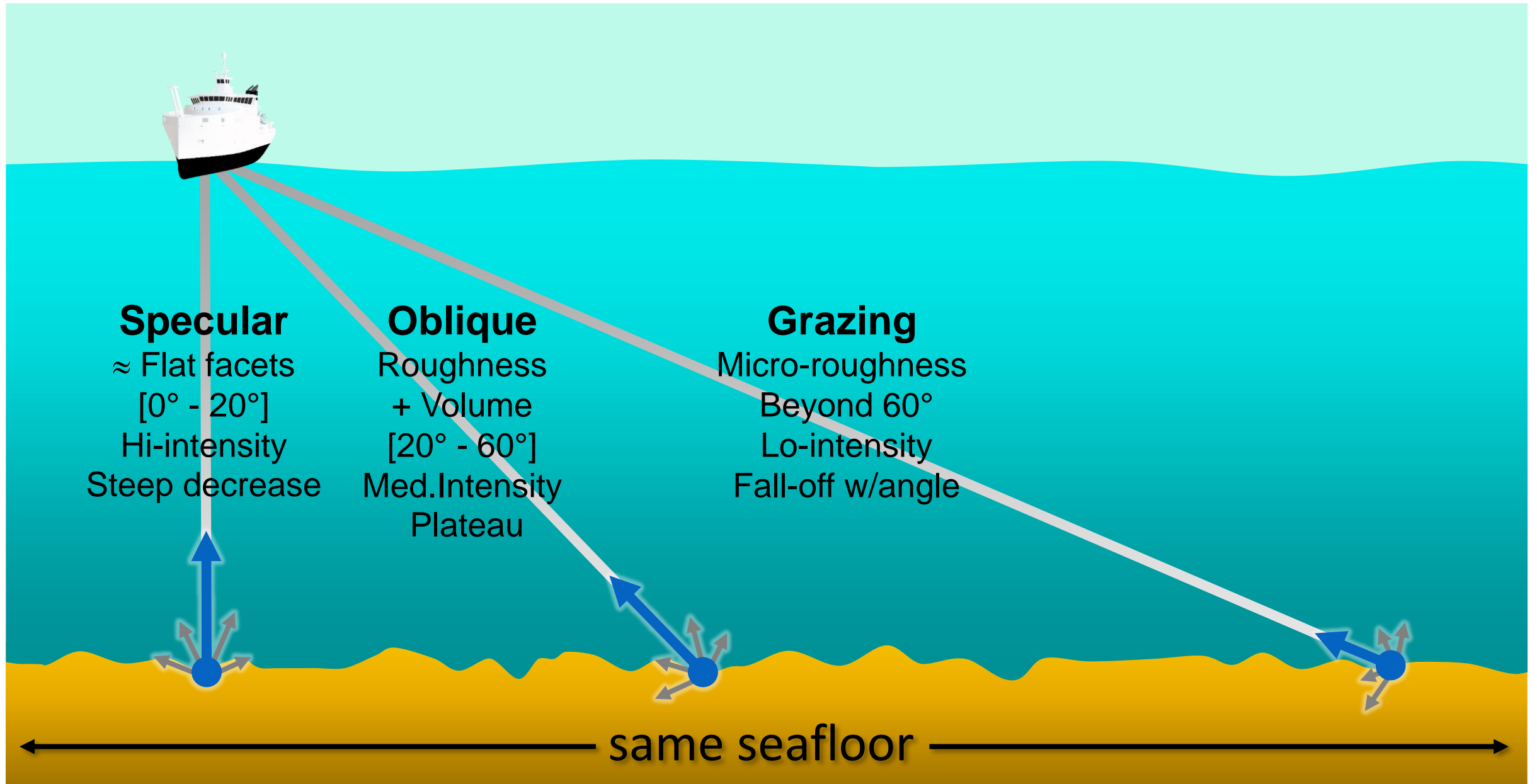
- Some of the incident acoustic energy may penetrate the sediment and be scattered by heterogeneities such as :

- mineral inclusions
- Biological diffusers
- Gas bubbles
- ...

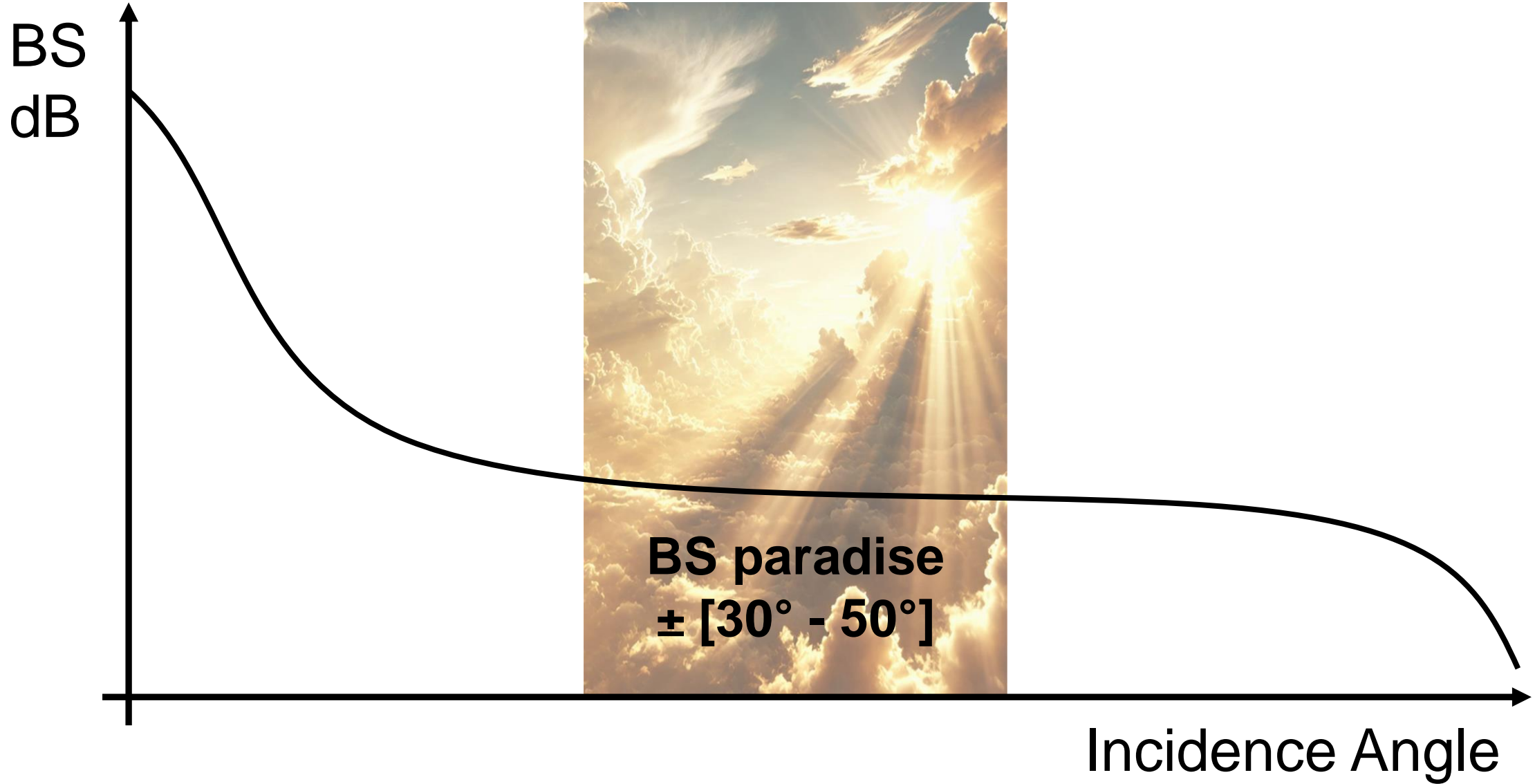


- Often prevalent at intermediate oblique incidence
- Relies on the acoustic wave penetration in the sediment
- Very strong influence of frequency (Low F \leftrightarrow High F)

Angular dependence: scattering regimes vs Angle



BS Angular Response



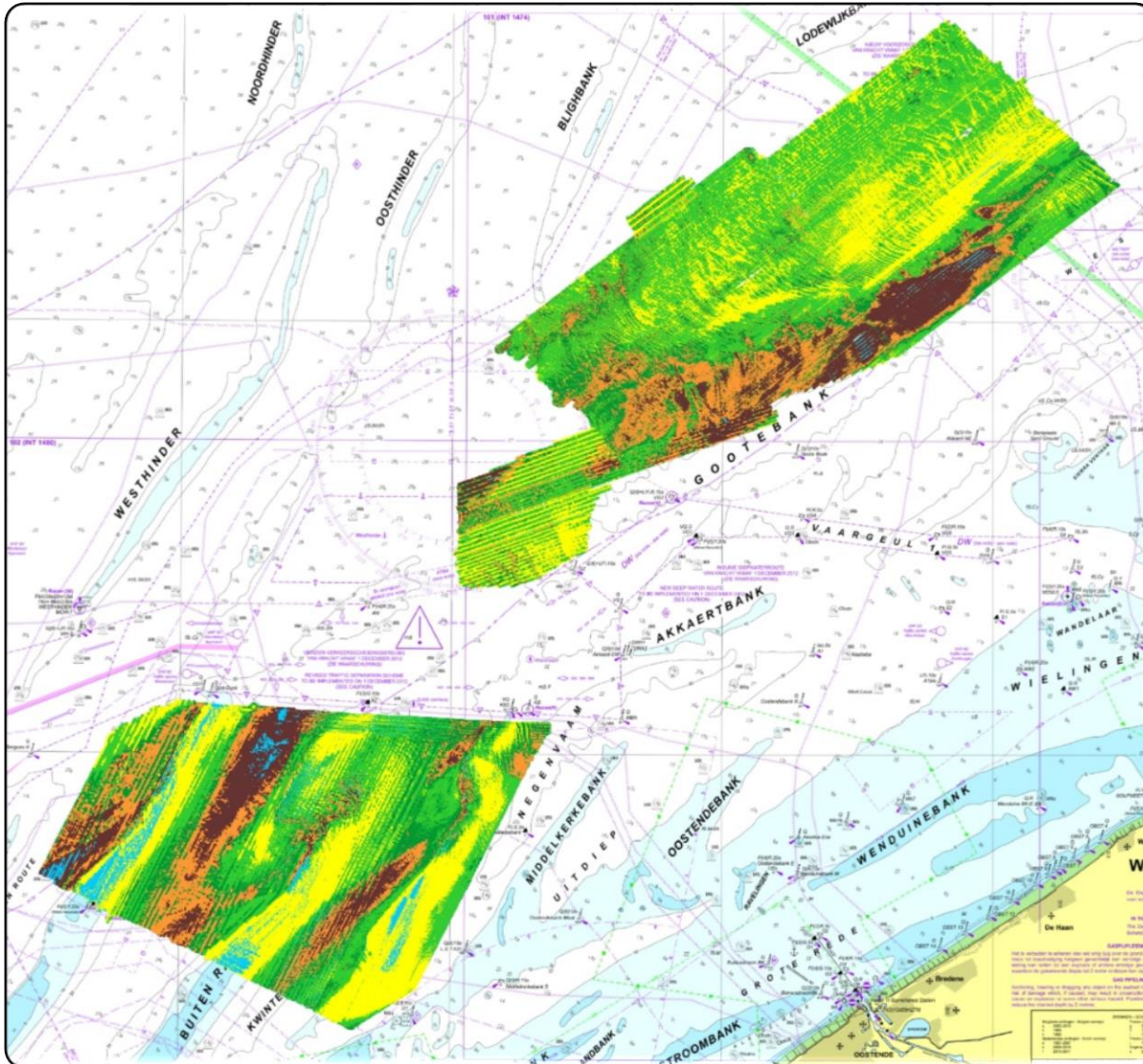
Using BS in relation to sand extraction

Illustrated by case studies

1. For surface sediment mapping
2. As a proxy for assessing the impact of extraction on the nature of the sediment
3. For tracking the sediment plumes
4. A few amusing anecdotes on BS...

Surface sediment mapping

Old RV Belgica
EM1002 100 kHz - 2005



Class 1

- Highest BS
- Clastic gravel in a sandy or muddy matrix, sandy gravel
- Gravel fields in the swale
- Typical " hillhocky " morphology



Class 2

- Moderate BS
- Gravely bioclastic sands (shells or shell debris)
- Sand dune fields in the swale and on the bank
- Most exploited granulate



Class 5

- High BS
- Fine muddy sand, few shells, Lagis koreni bioturbation
- Flat area in the swales



Class 3

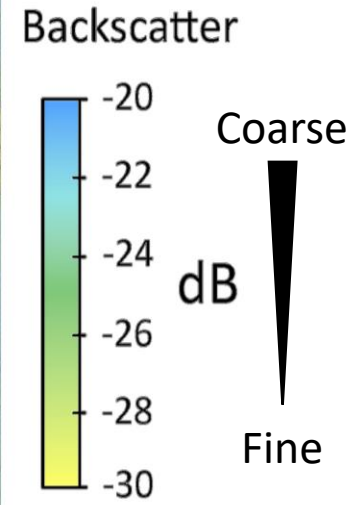
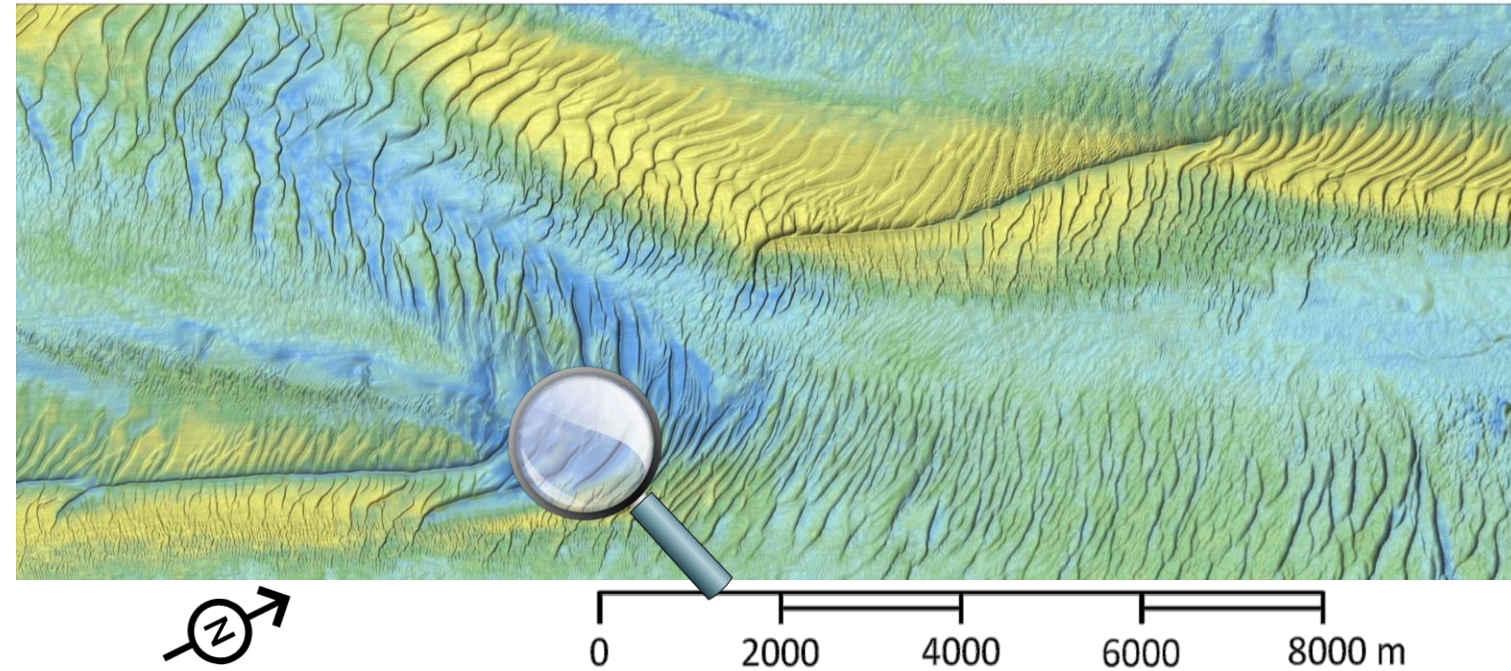
- Lowest BS
- Fine homogeneous sand
- Shallowest areas



Outlier

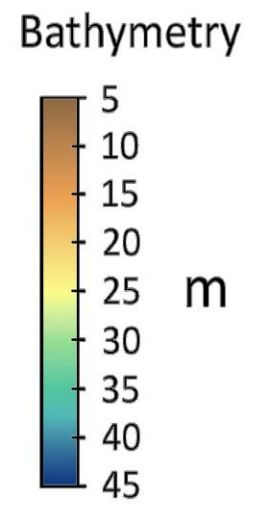
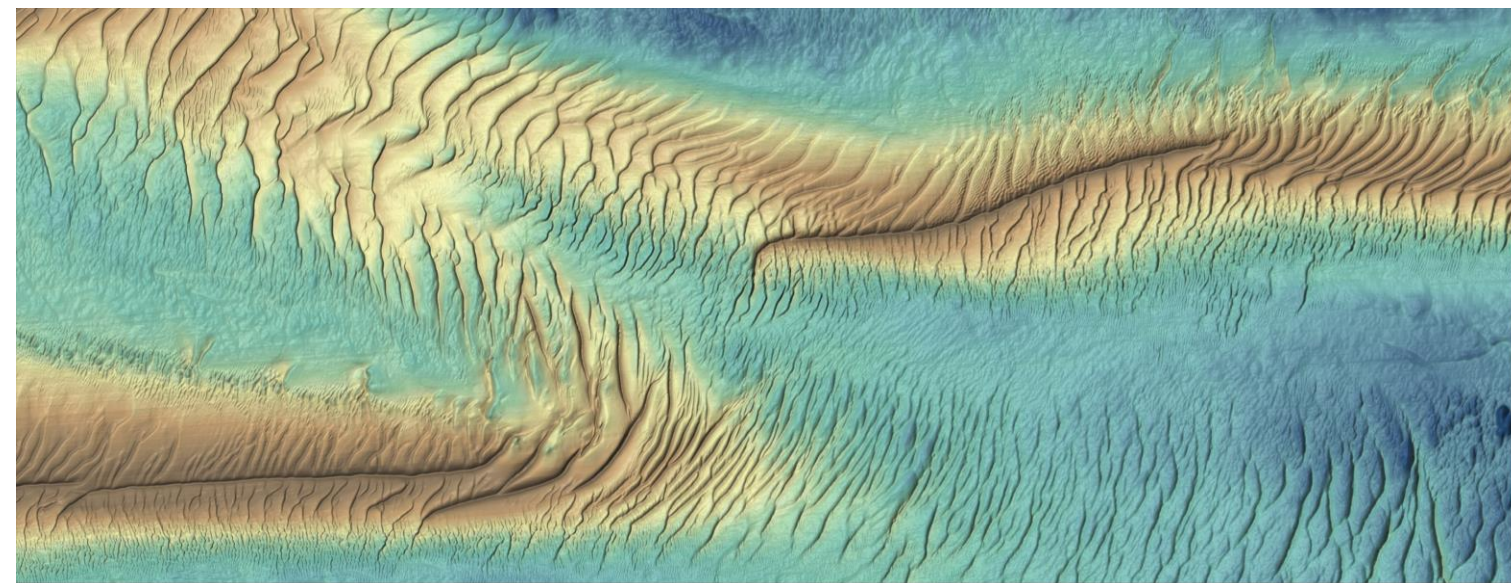


Surface sediment mapping

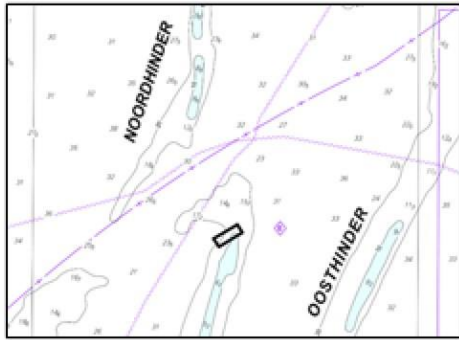


Westhinder and Noordhinder

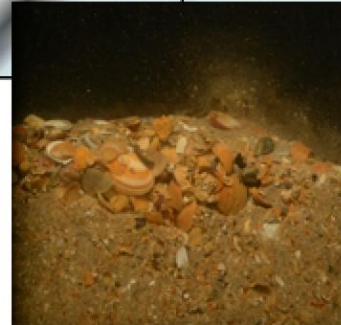
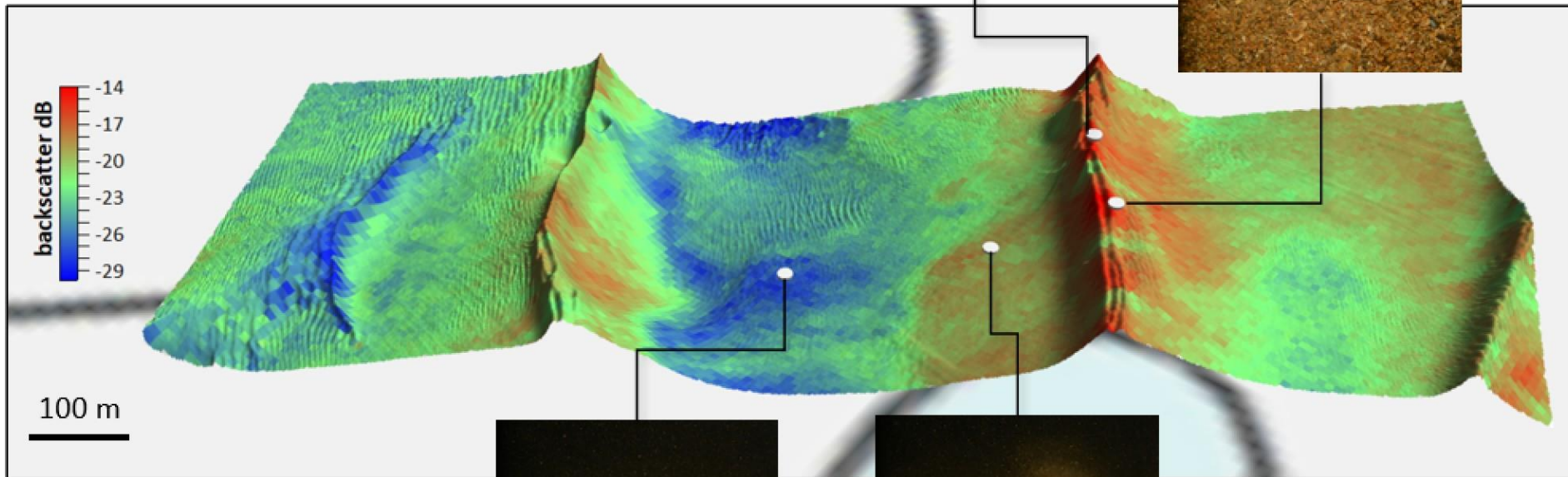
Old RV Belgica
EM3002D 300 kHz
2012



Surface sediment mapping



Westhinder
RV Simon Stevin
EM2040D 300 kHz
2022

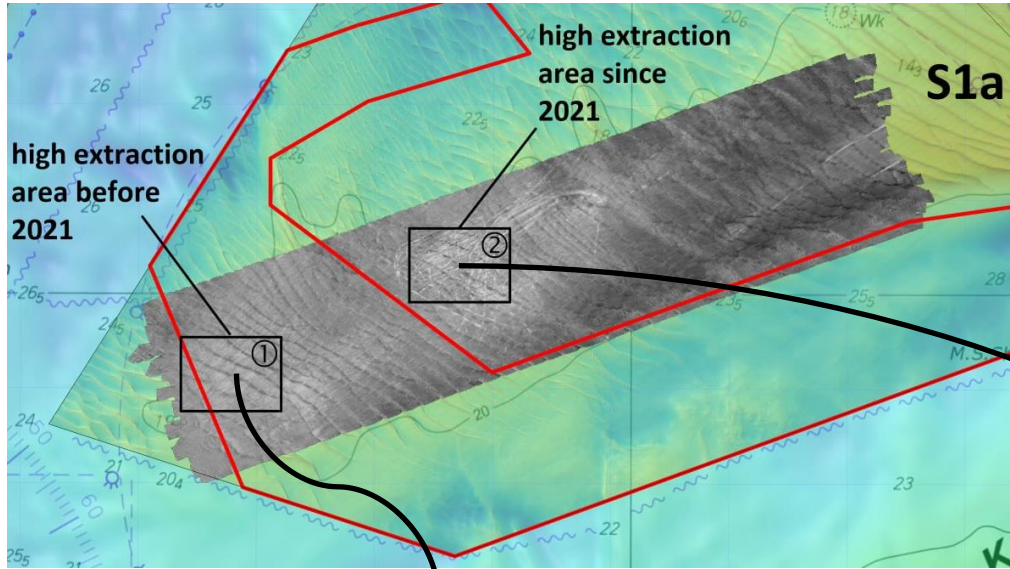


Sediment profile imaging

15 cm



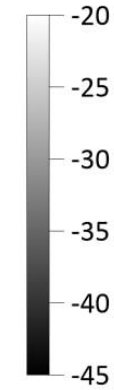
Surface seafloor mapping



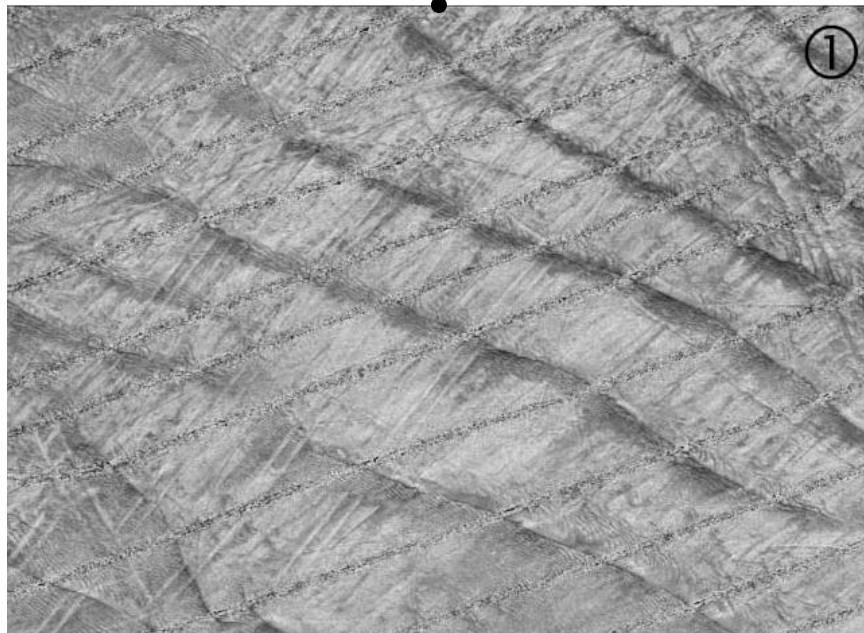
closed to sand extraction since 01/01/2021



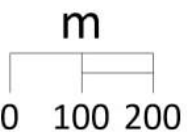
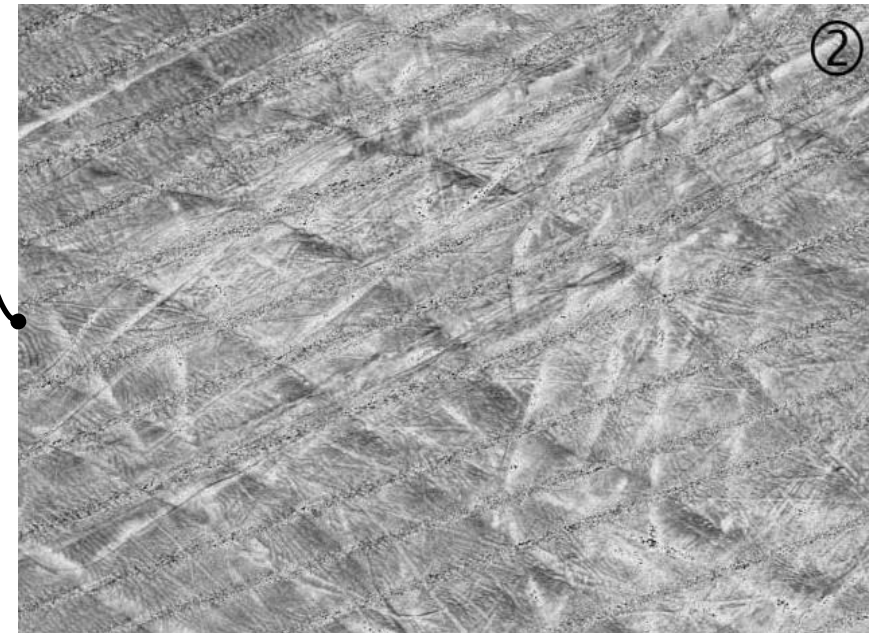
BS dB



Thorntonbank
Old RV Belgica
EM3002D
300 kHz
2021



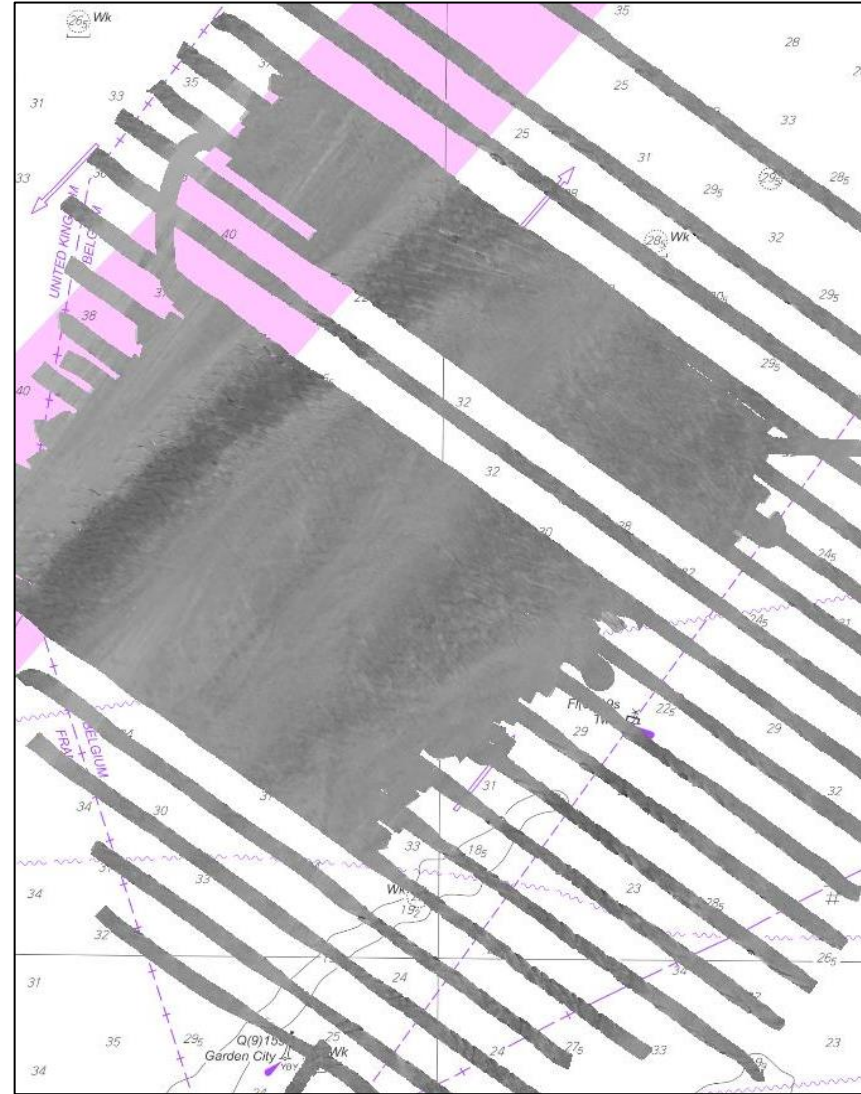
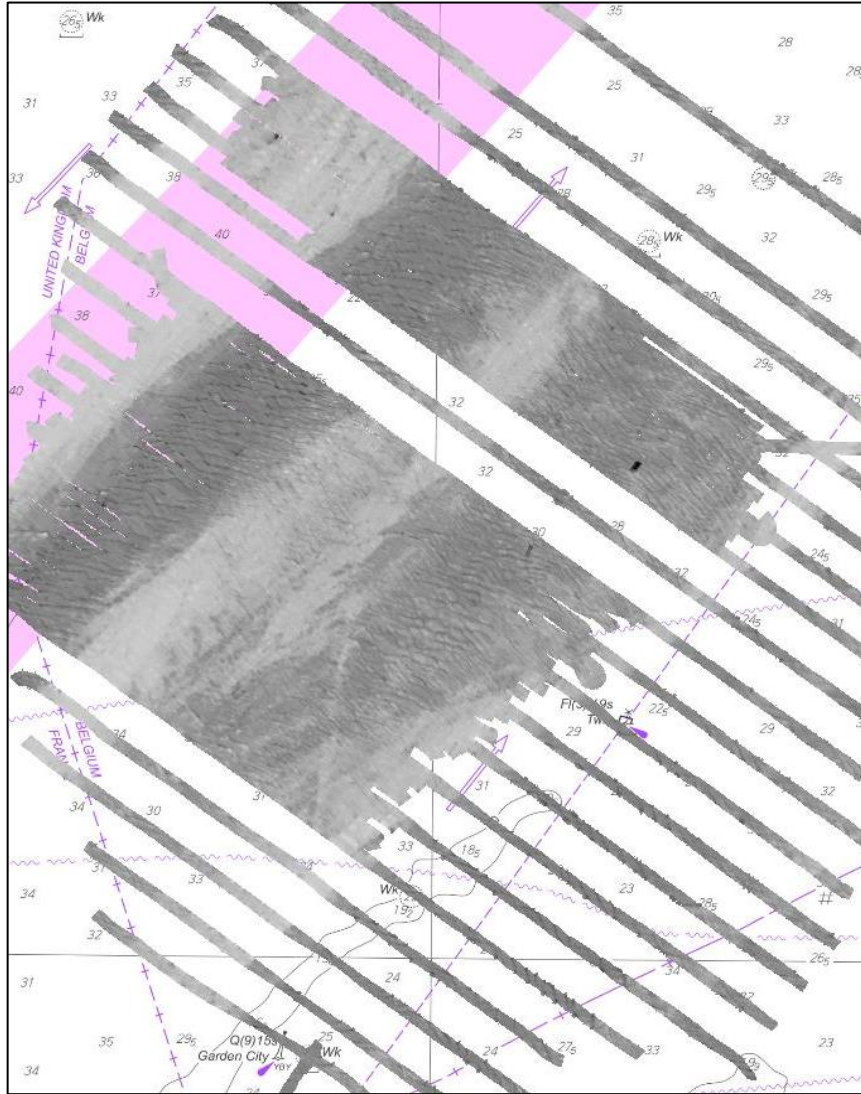
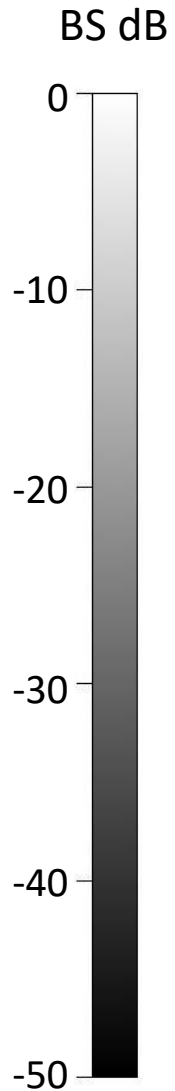
Intensive dredging



Surface sediment mapping

RV Belgica EM304 – 30 kHz

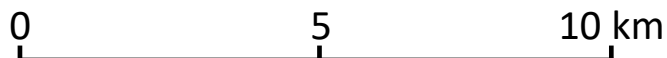
RV Belgica EM2040 – 300 kHz



Exploration
area

2022

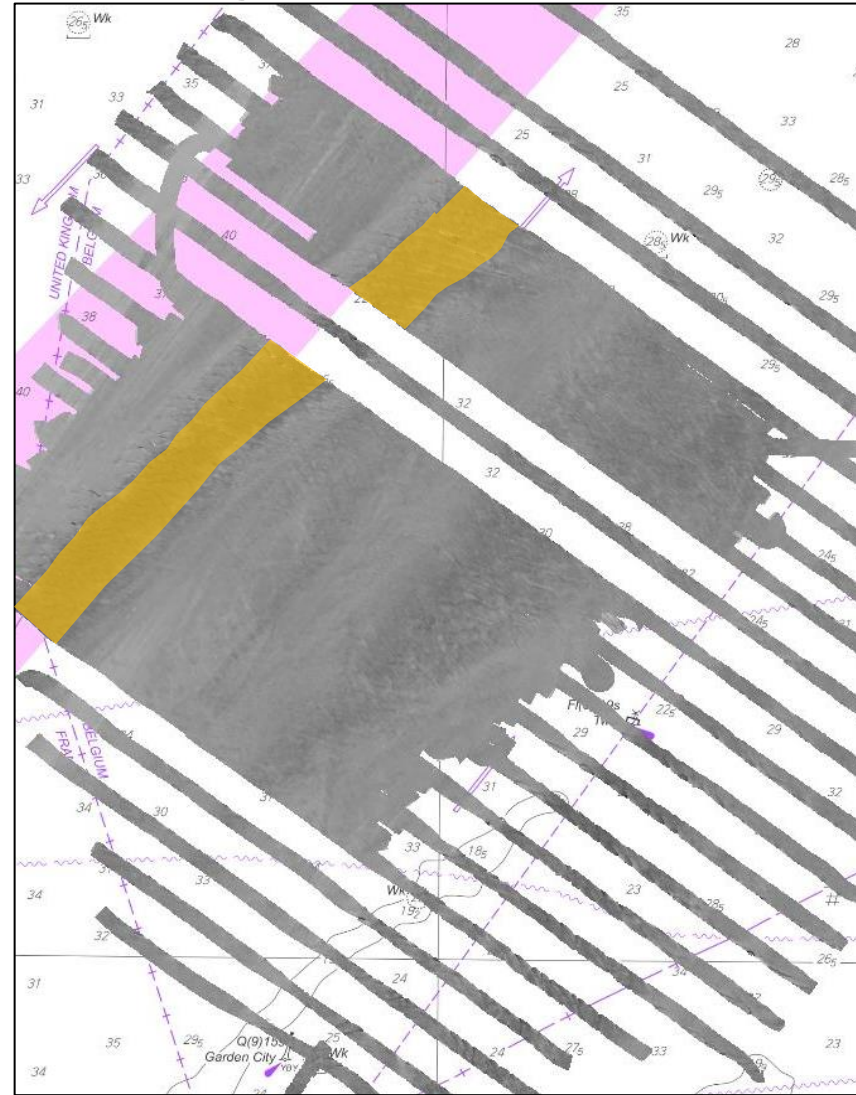
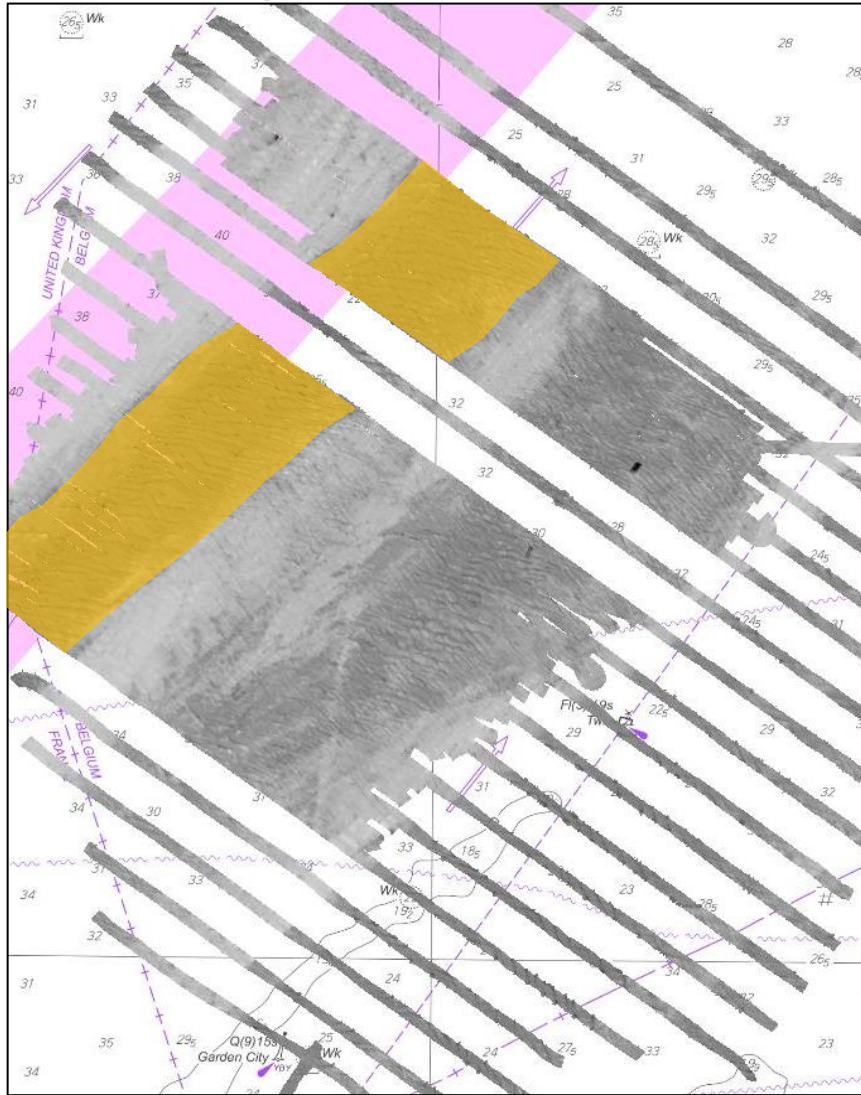
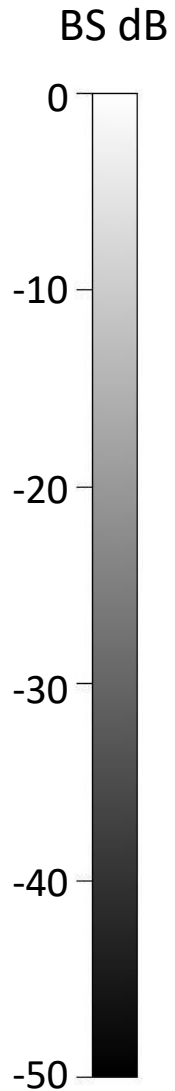
Δ Octave
= 3.32



Surface sediment mapping

RV Belgica EM304 – 30 kHz

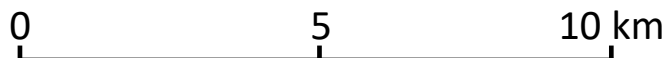
RV Belgica EM2040 – 300 kHz



Exploration
area

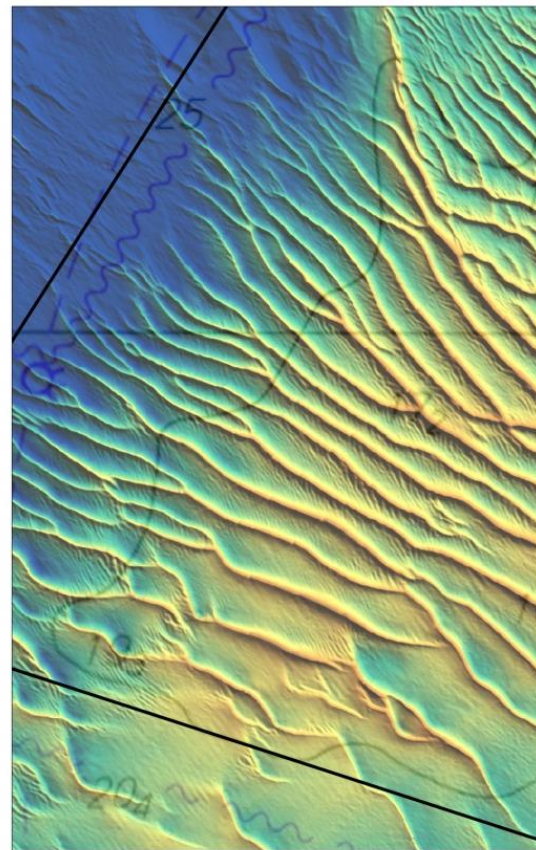
2022

Δ Octave
= 3.32



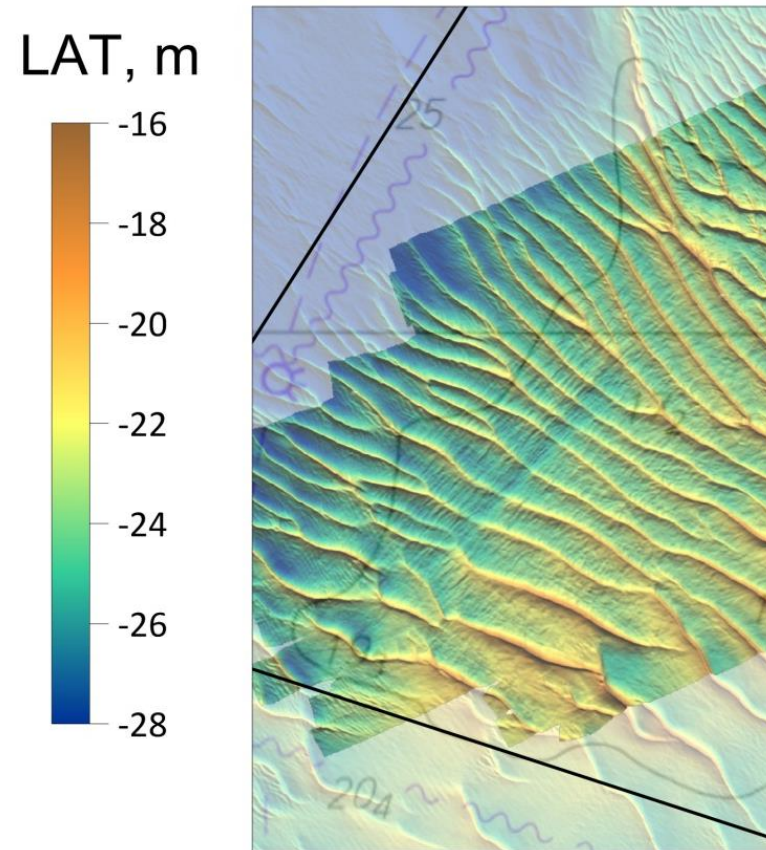
BS for monitoring the seabed: *Case study 1 - Thorton bank SW*

ref 2002

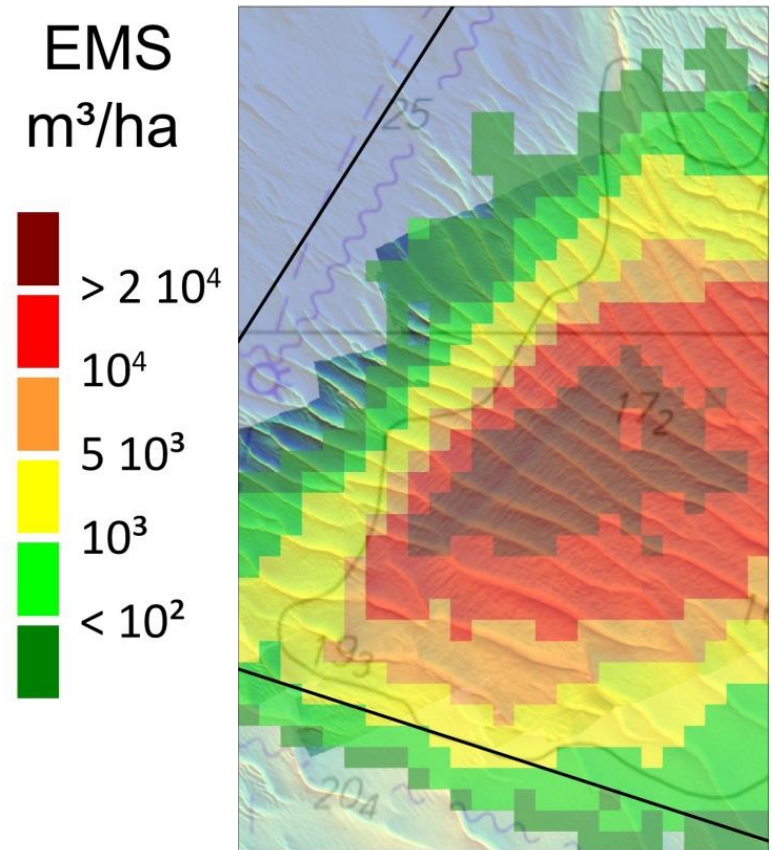


0 500 1000m

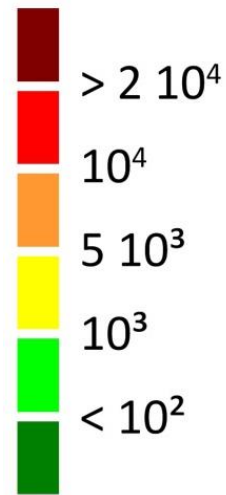
03/2018



2006-2017

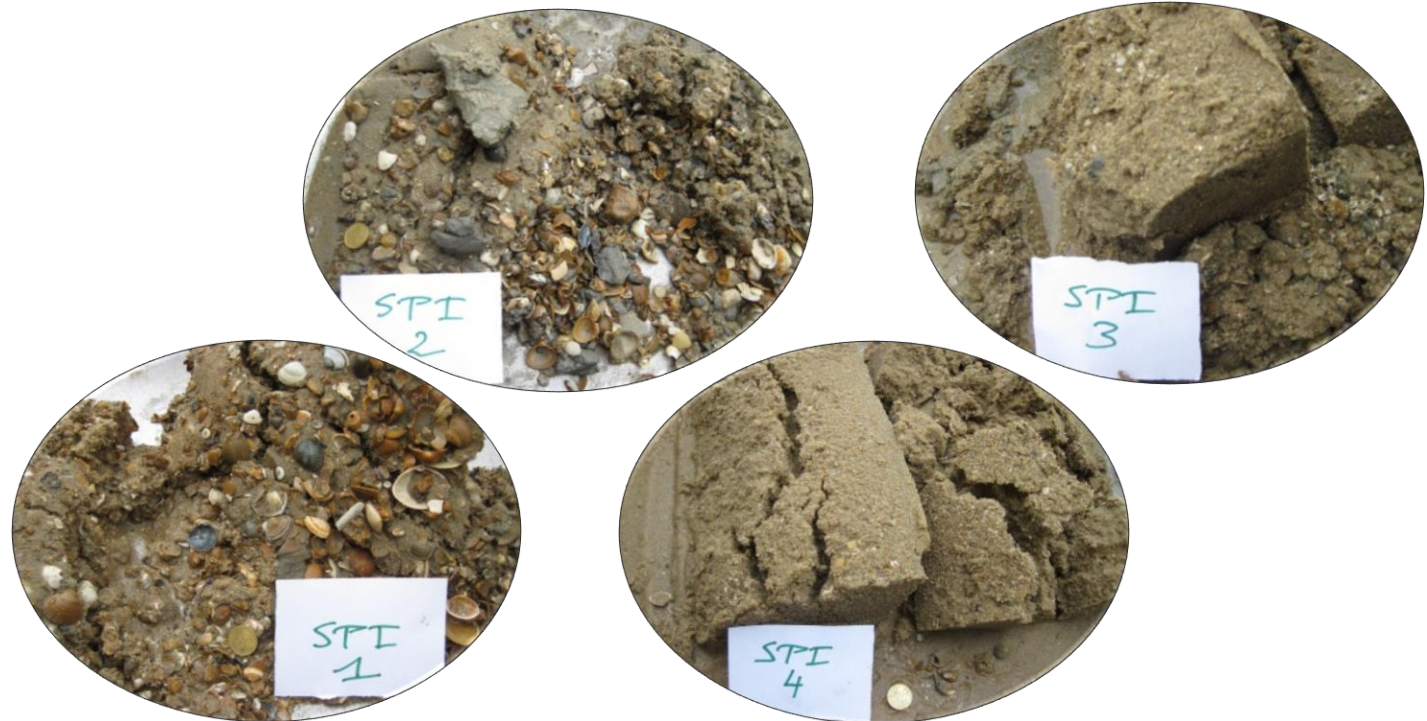
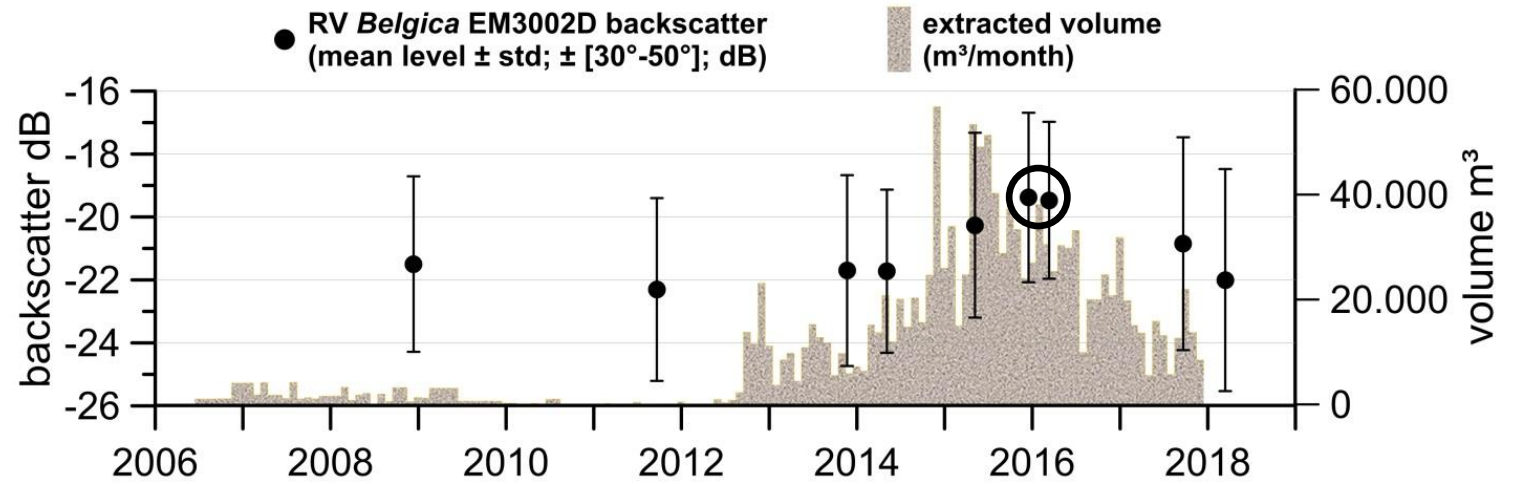
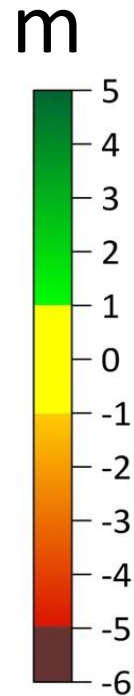
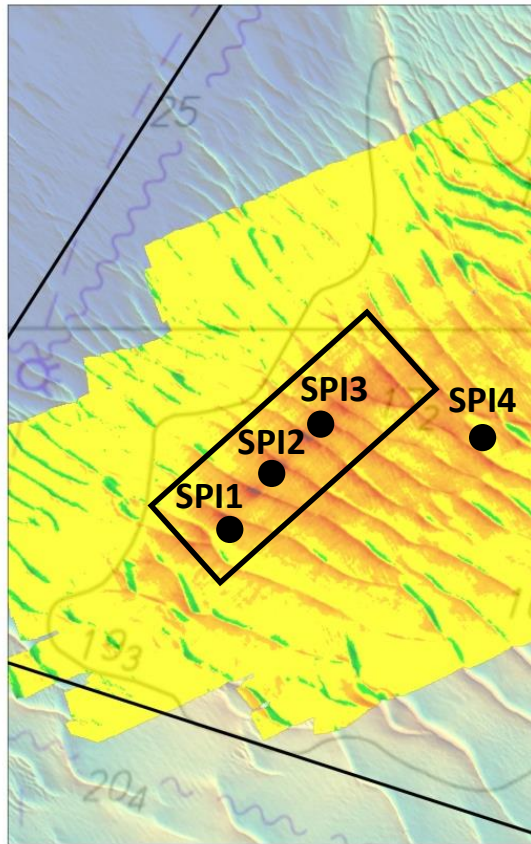


EMS
m³/ha



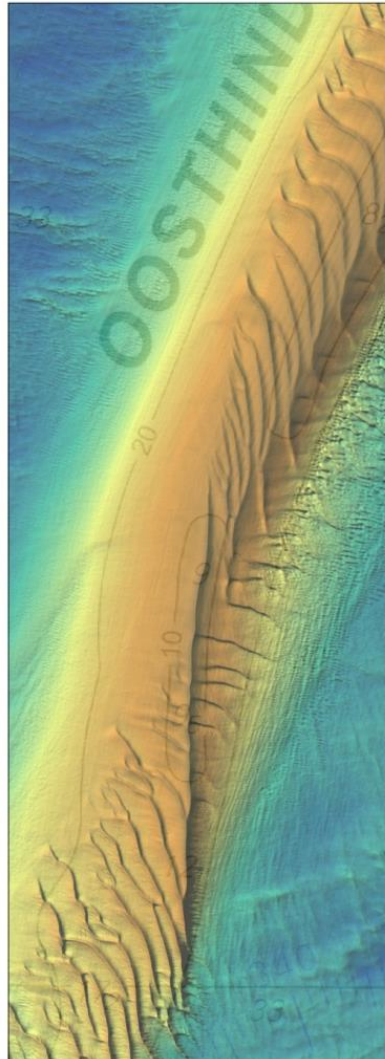
BS for monitoring the seabed: *Case study 1 - Thorton bank SW*

△
ref 2002 – 03/2018

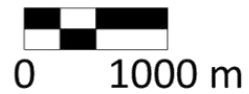
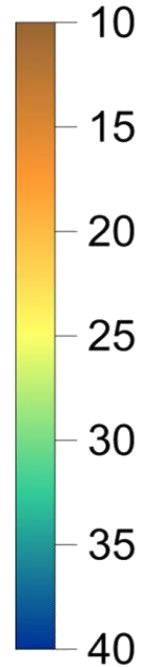


BS for monitoring the seabed: *Case study 2 – Oosthinder Bank*

ref 2005



LAT, m



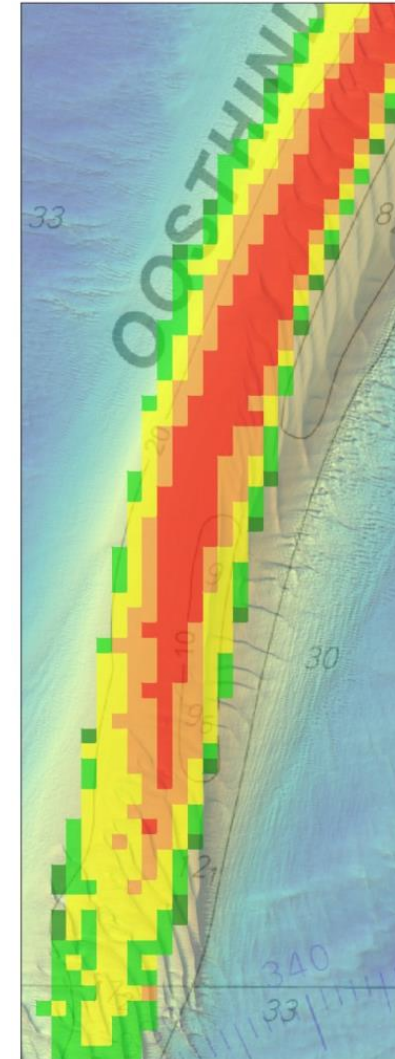
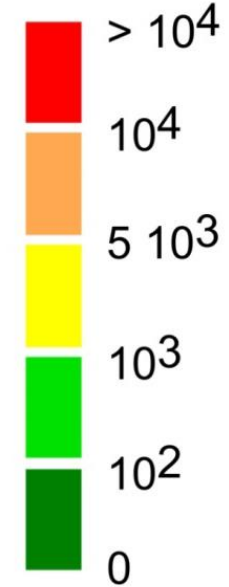
03/2018



2012-2017

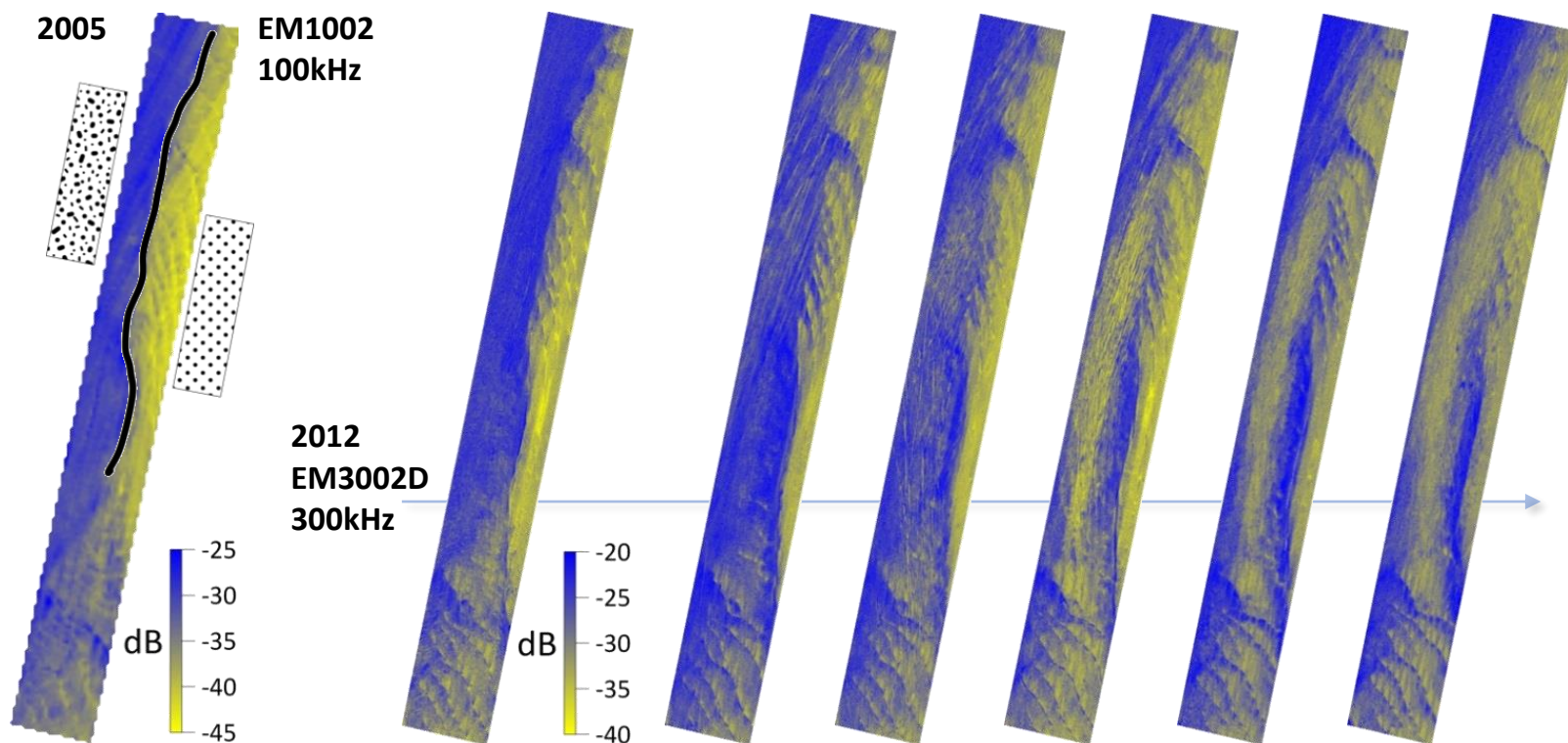
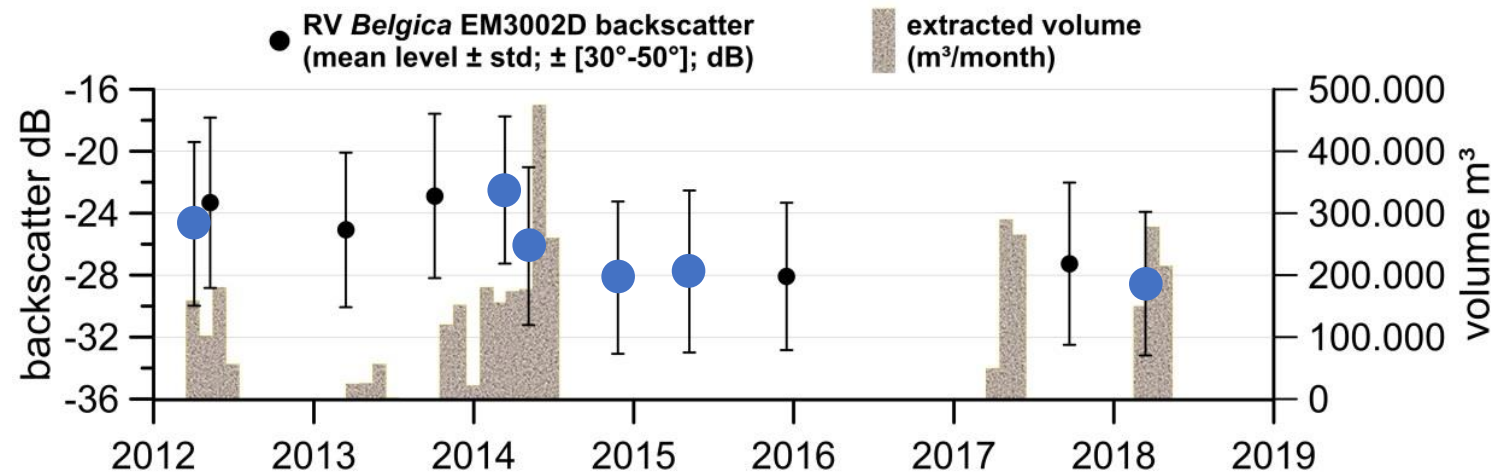
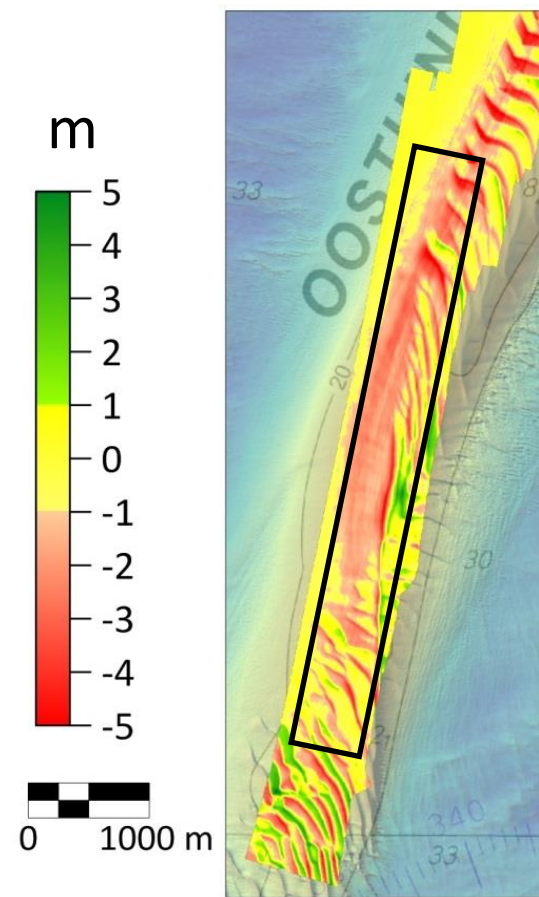
EMS

m³ / ha

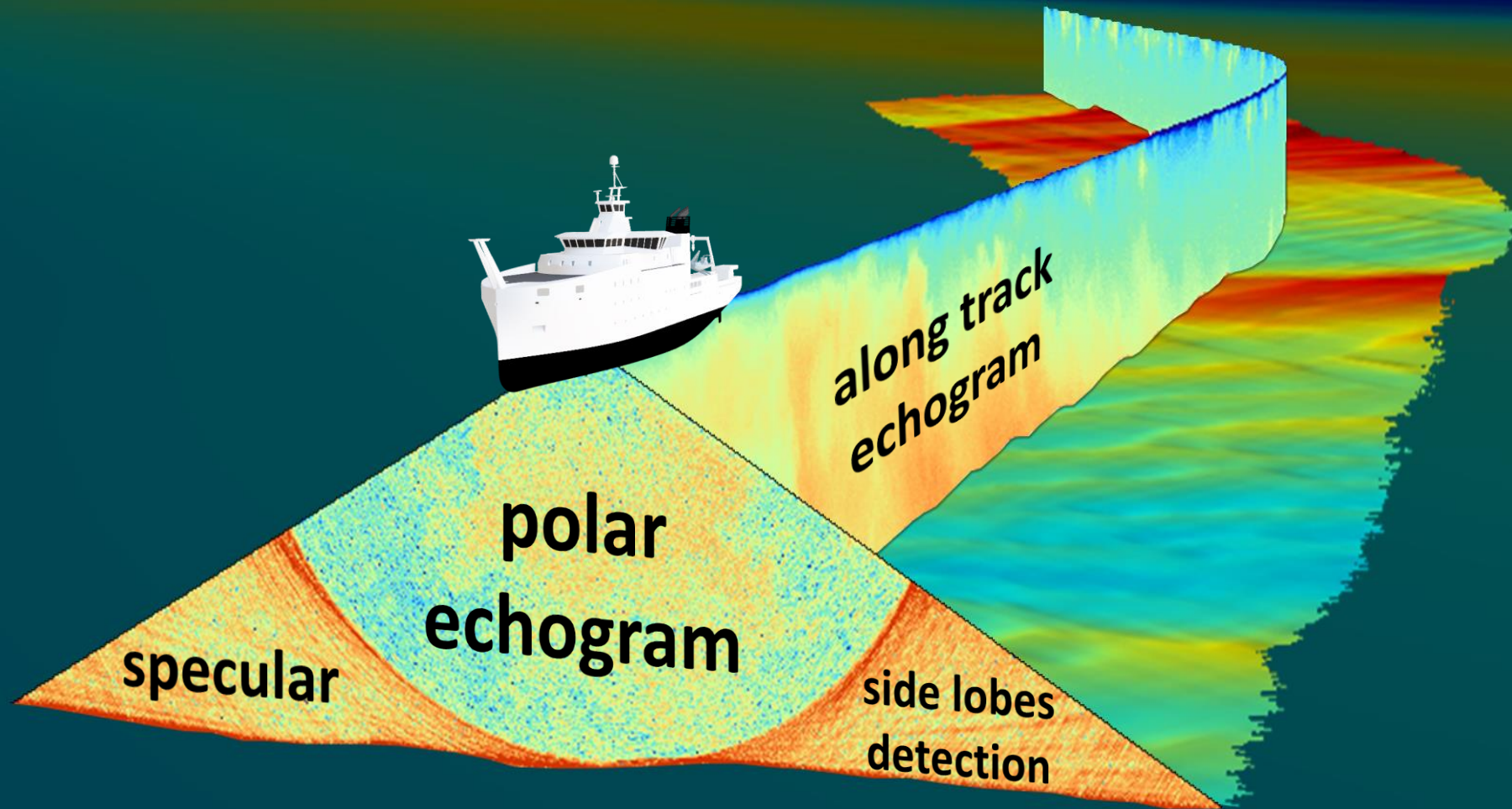


BS for monitoring the seabed: *Case study 2 – Oosthinder Bank*

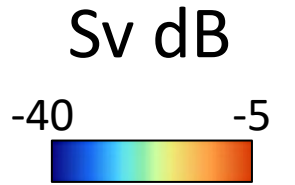
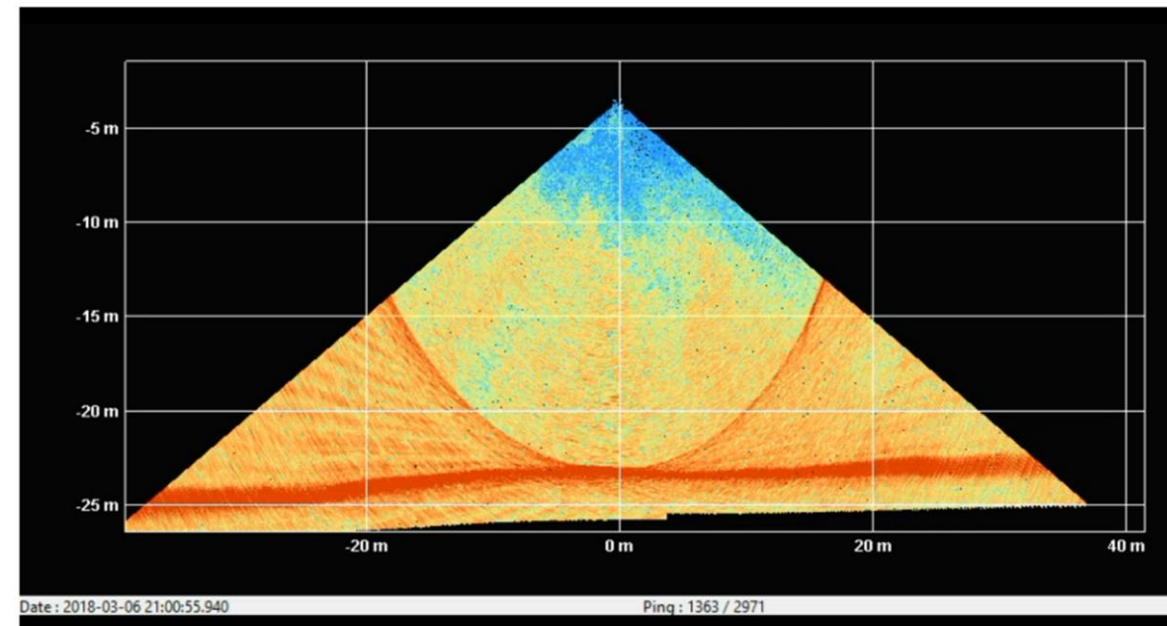
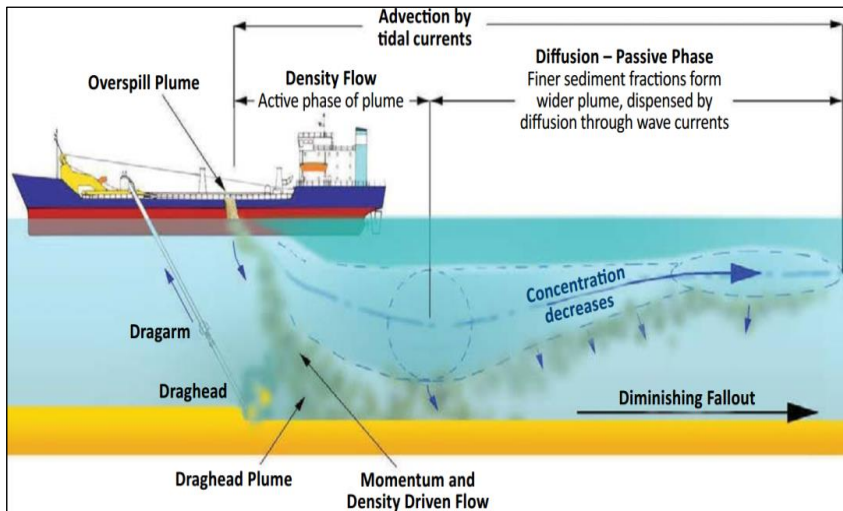
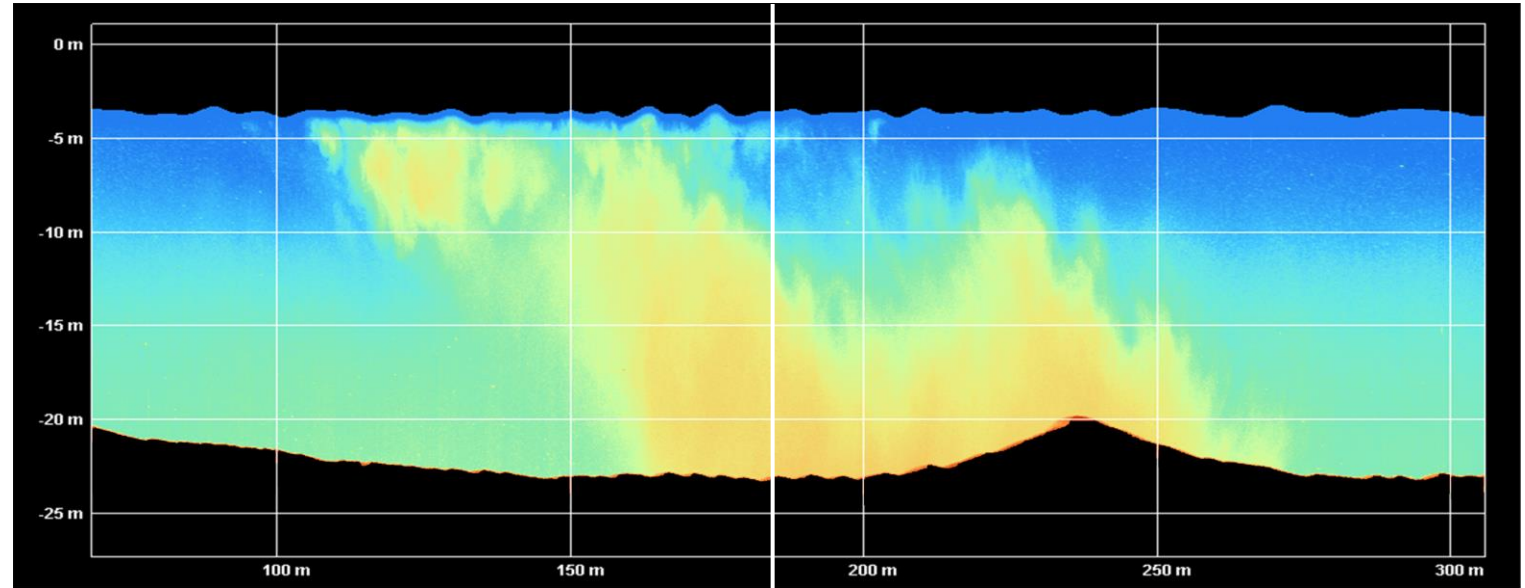
△
ref 2005 – 03/2018



Water column BS



Water column BS for tracking the sediment plumes



RV Simon Stevin
EM2040 300 kHz
19/03/2023

Date: 2018-03-06 21:00:55.940

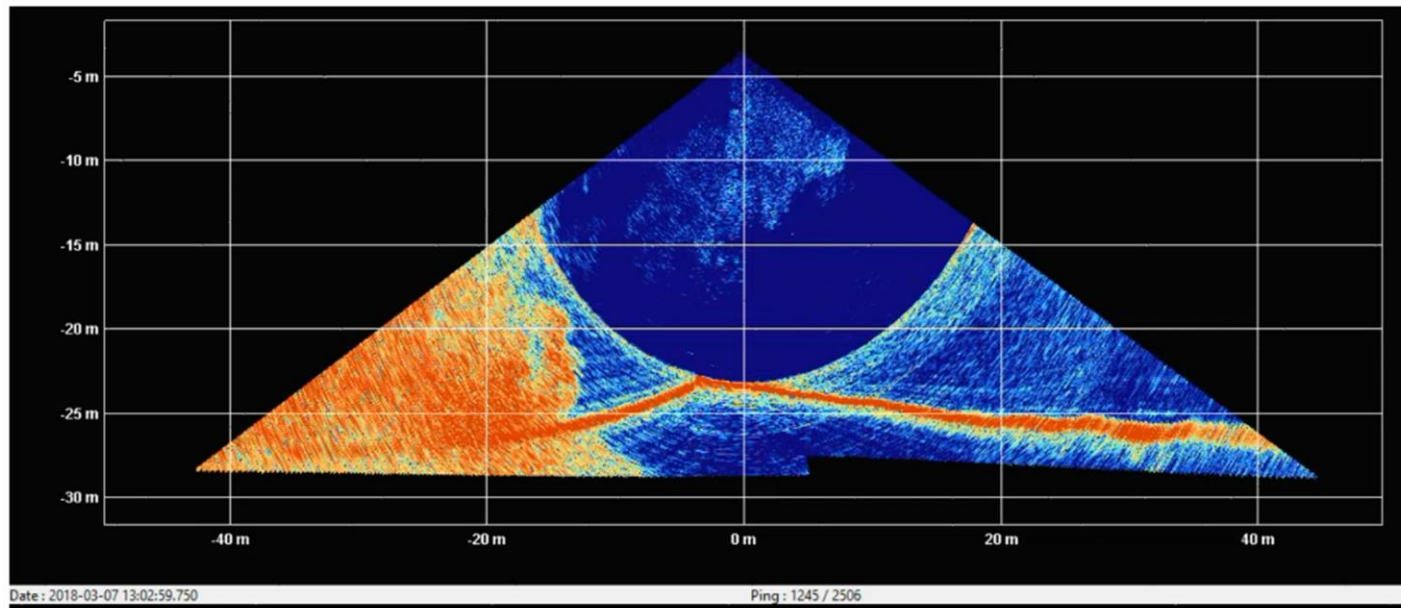
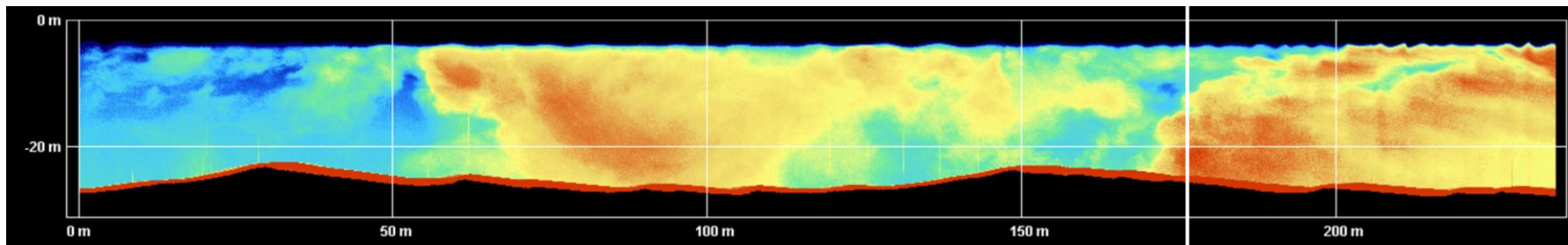
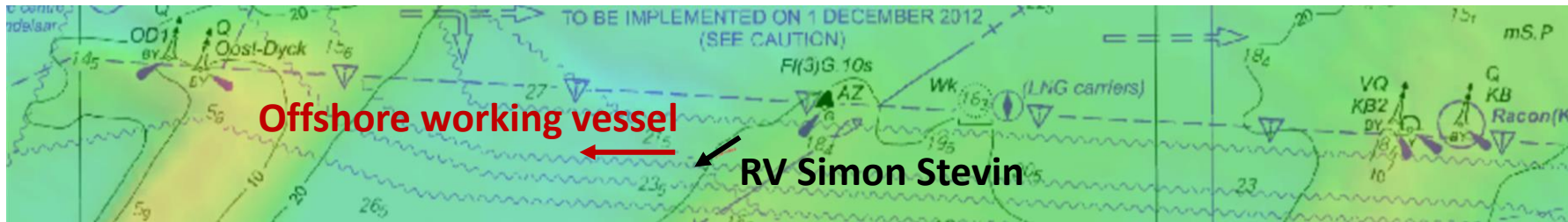
Ping: 1363 / 2971

Water column BS for tracking the sediment plumes

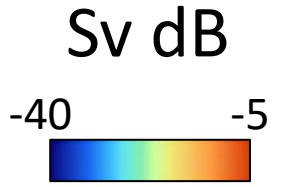
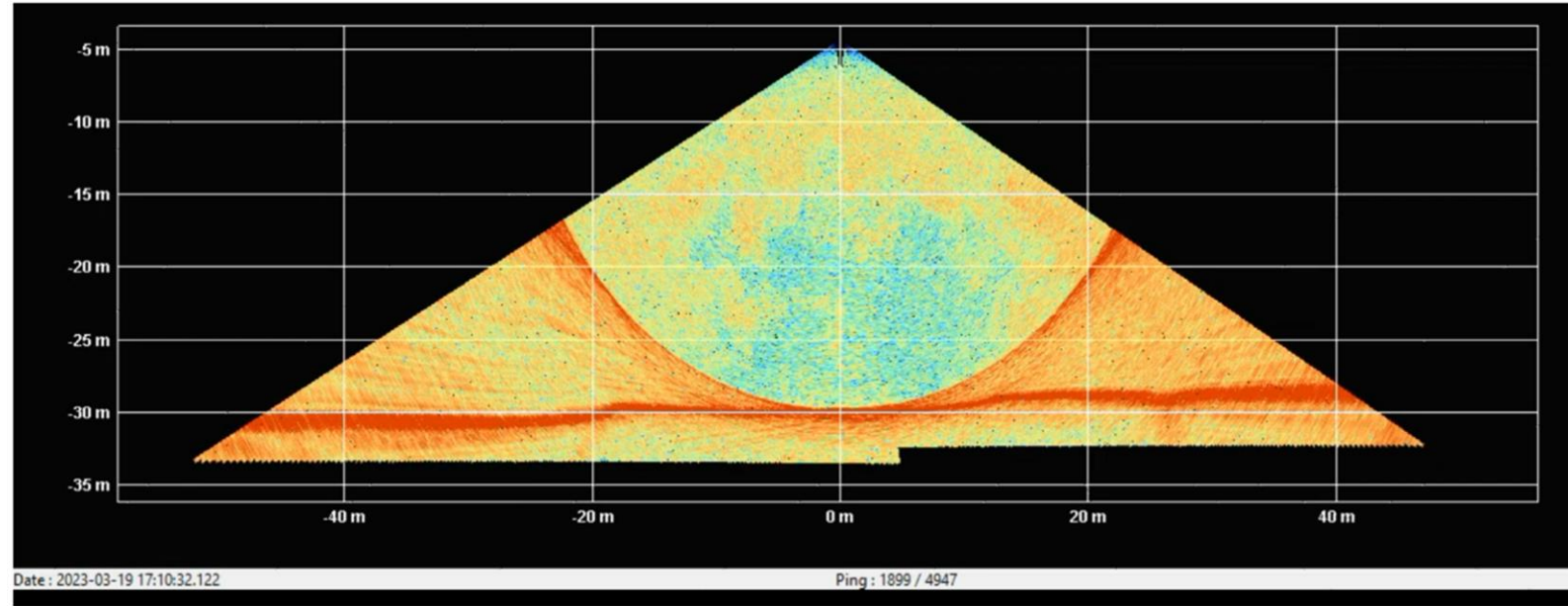
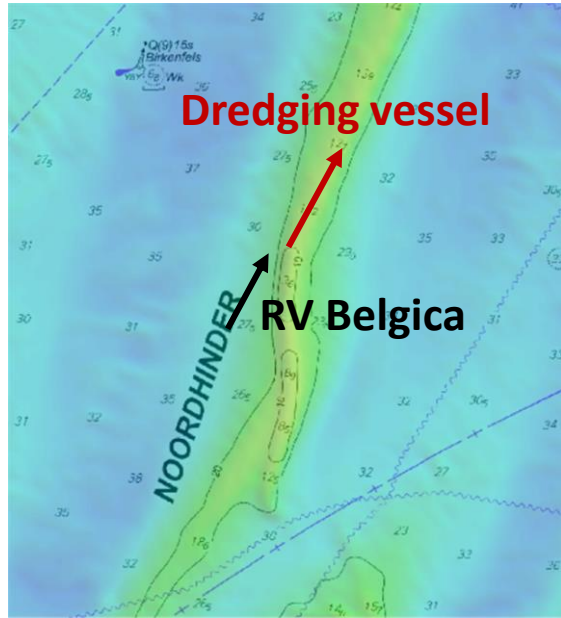
A colossal plume generated by offshore work



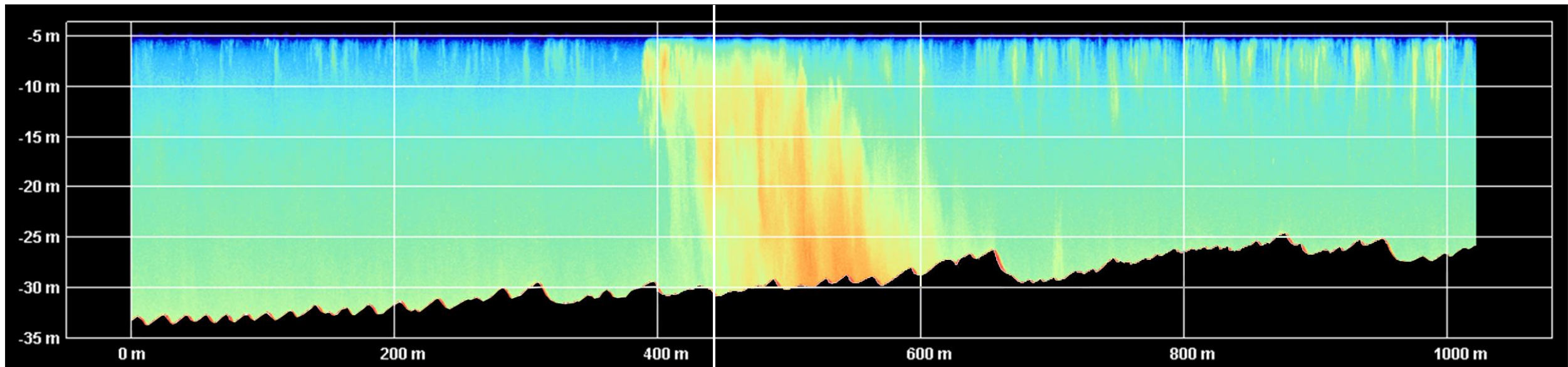
RV Simon Stevin
EM2040 400 kHz
07/03/2018



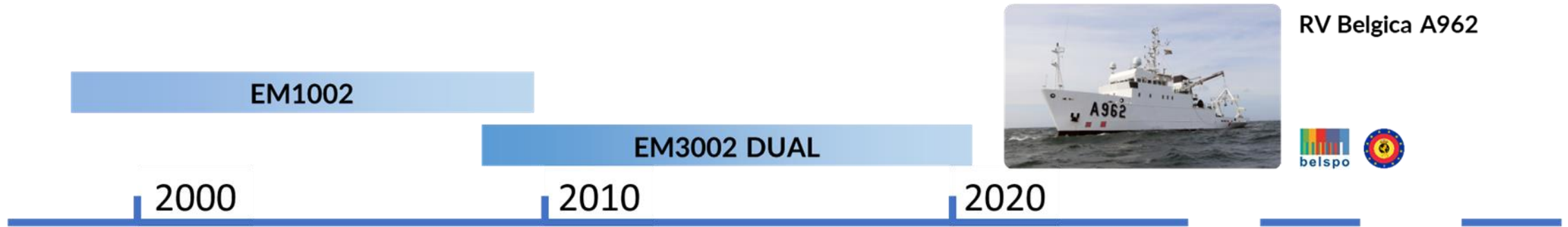
Water column BS for tracking the sediment plumes



RV Belgica
EM2040 300 kHz
19/03/2023



BS Calibration is now absolutely necessary!



RV Belgica A962



EM2040 DUAL RX

New RV Belgica



EM2040 DUAL RX

RV Simon Stevin



EM2040 DUAL SWATH

HV Sirius

AGENCY FOR
MARITIME &
COASTAL SERVICES



Optimal sharing of BS data

≠ MBES

≠ Acquisition mode

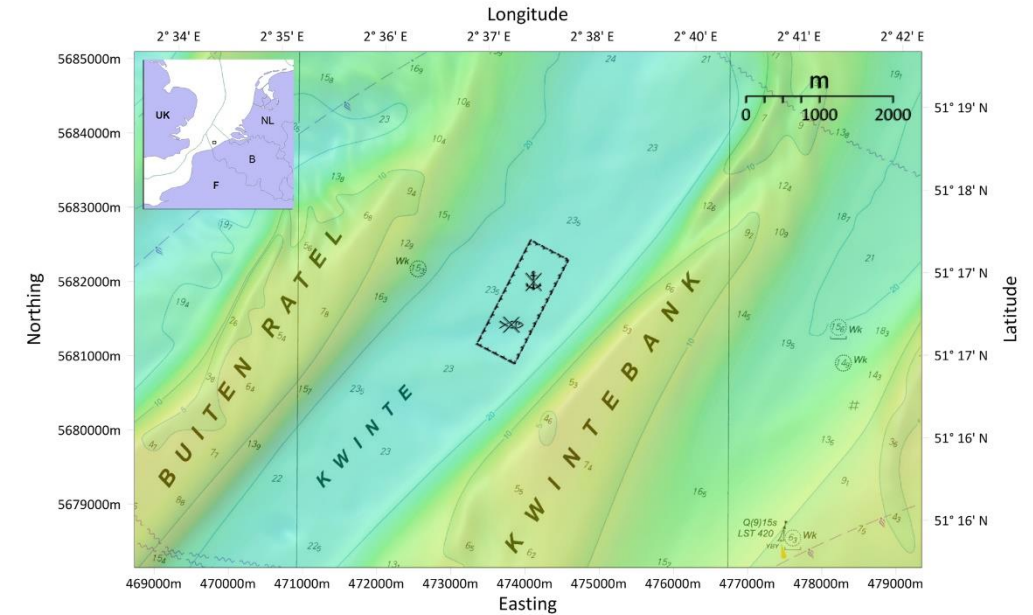
For integration in seabed
sediment mapping and
monitoring

➤ **Calibration**

BS calibration on reference area:

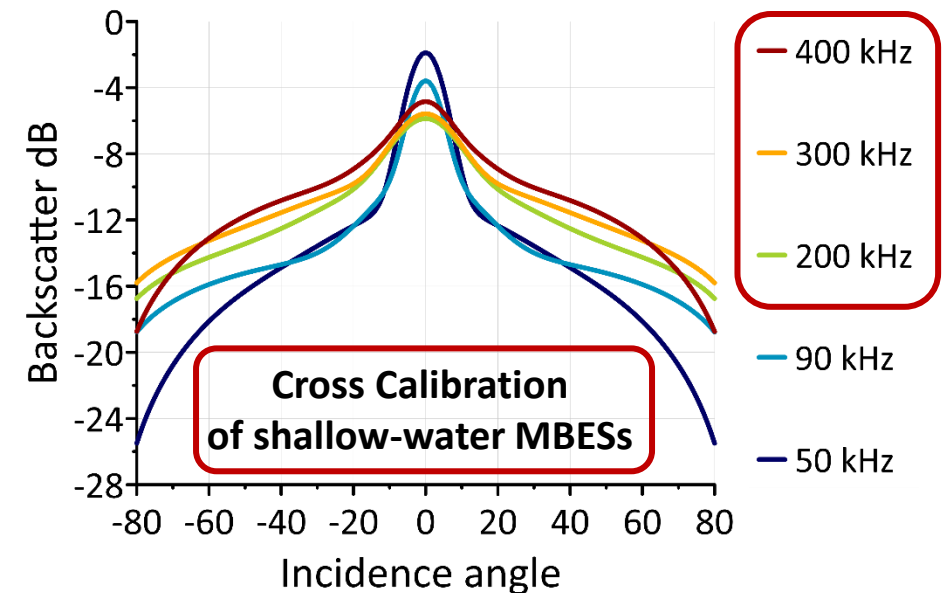
A reference area, e.g. Kwinte area (B)

- Mean backscatter level **stability = foundation**
- Flat morphology
- Homogenous sediment cover
- Open-Science compliant!

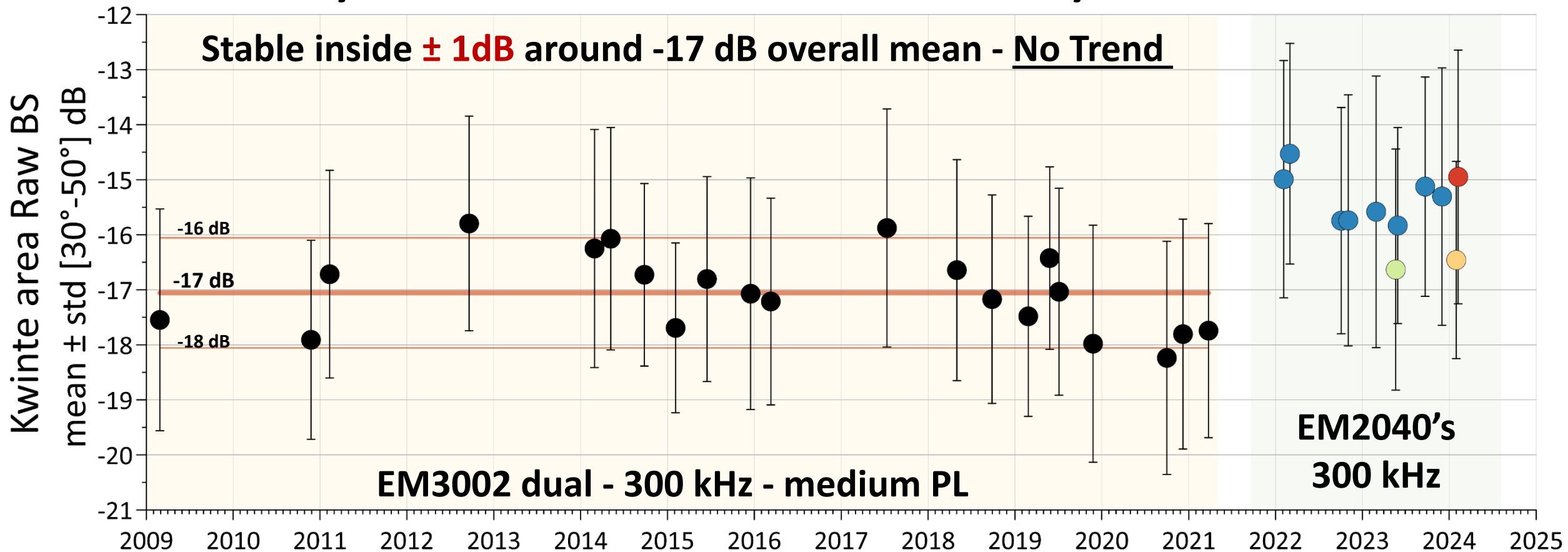


A reference angular response model

- Measured on reference area
- Using a fully calibrated Single Beam Echosounder
- One angular response per frequency



Stability must be demonstrated by time-series



The old time series

● RV Belgica A962



The new time series

● New RV Belgica



● RV Simon Stevin



● HV Sirius



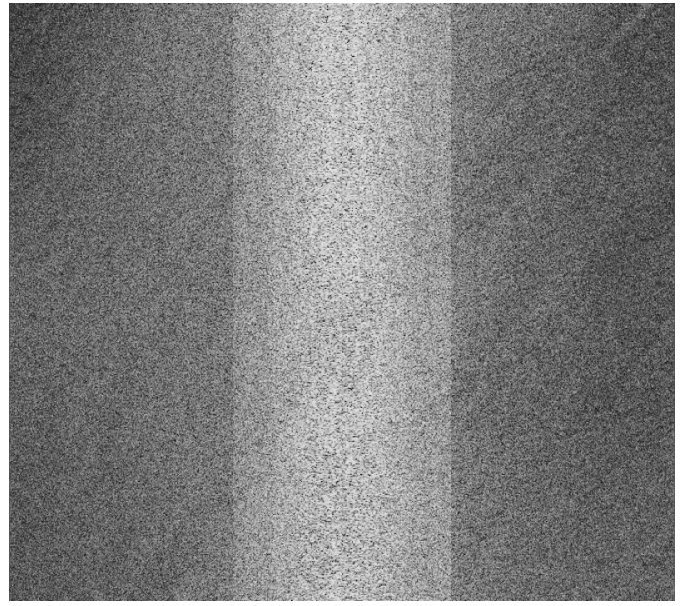
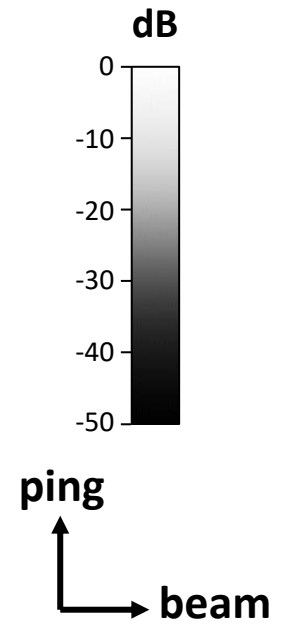
● RV Zirfaea



Recipe of BS calibration on reference area:

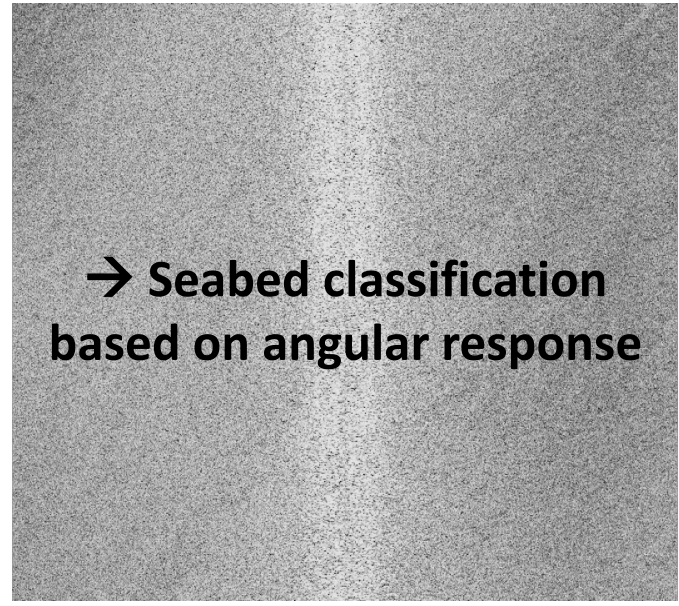
Raw BS

0004_20220204_052559_Belgica.all
300 kHz – normal mode – medium pulse length



Calibrated BS

+ beam pattern correction

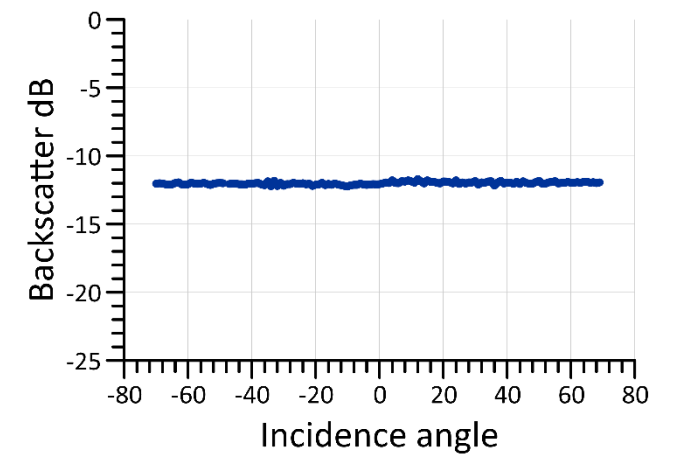
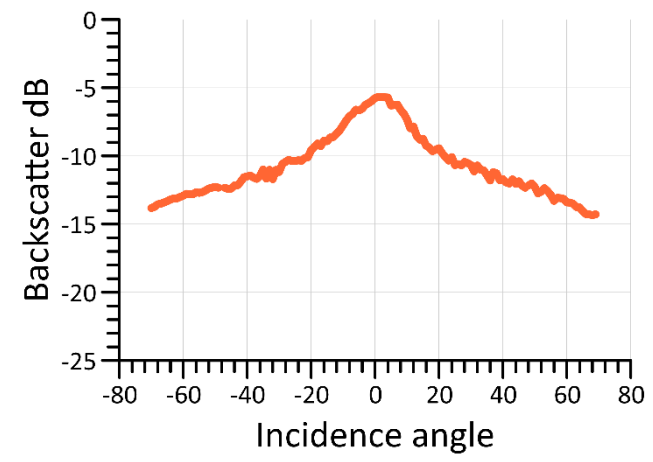
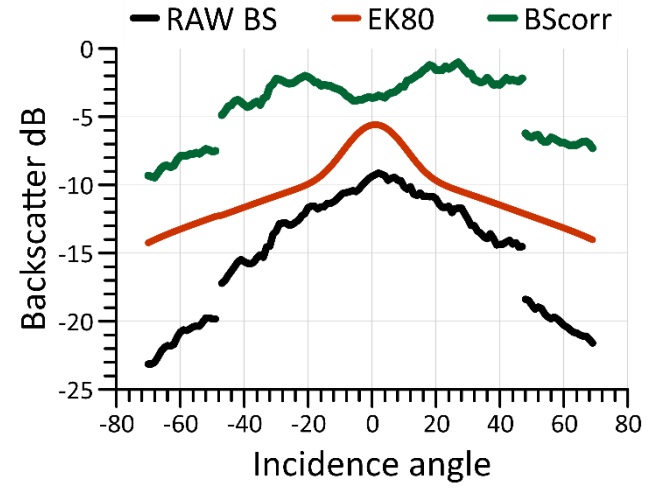


Calibrated BS

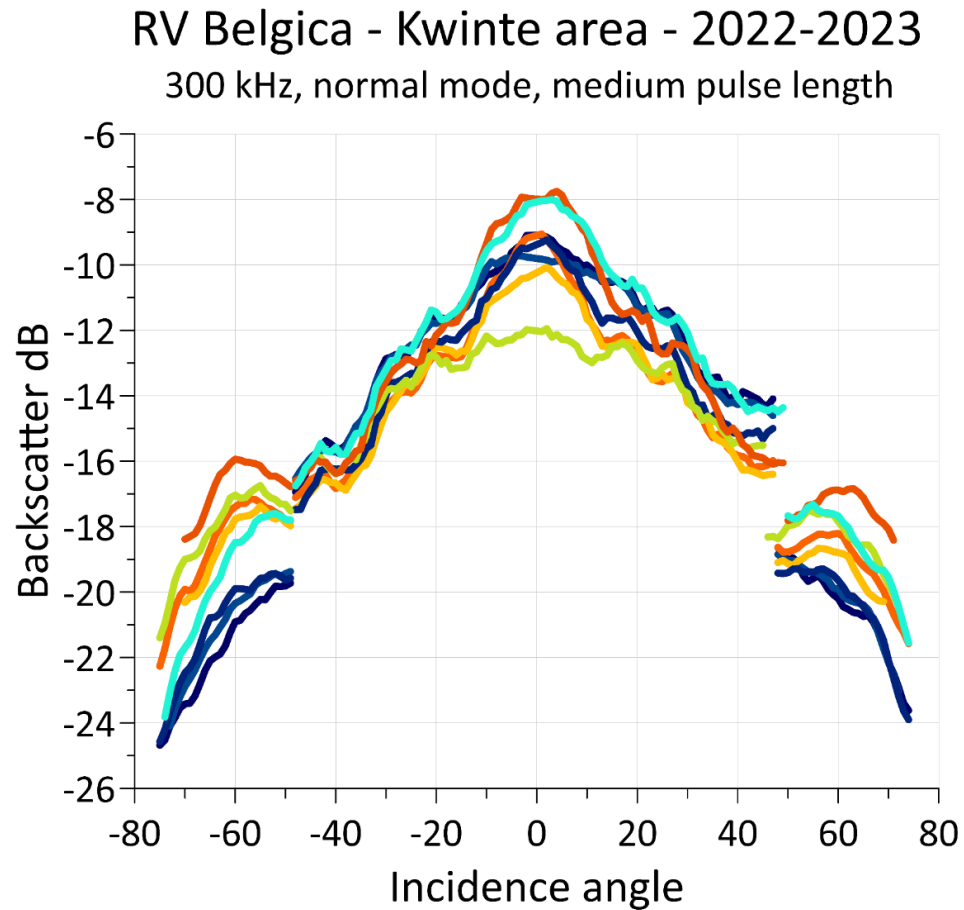
+ beam pattern correction
+ flattening – angular compensation



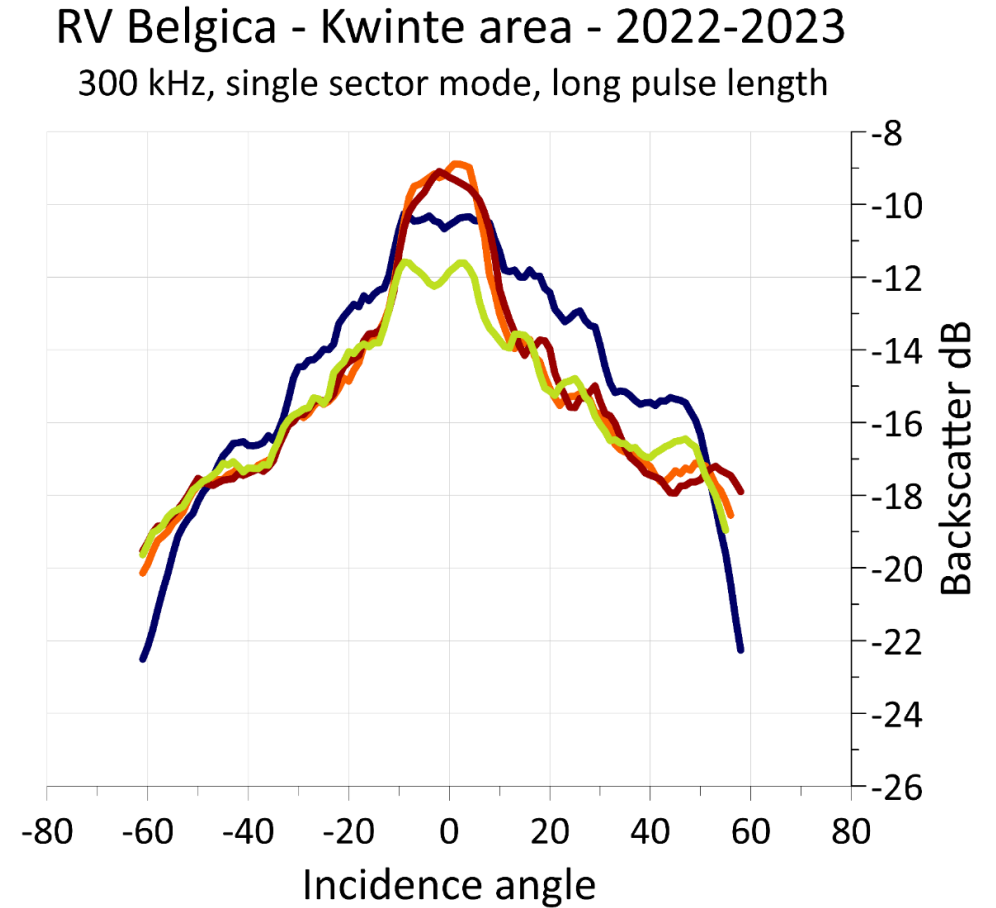
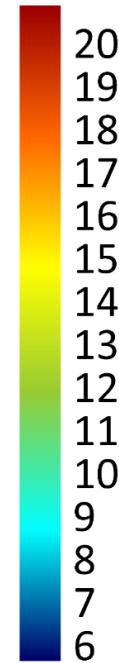
Raw BS
—
Calibrated SBES = Reference
—
BS correction = Reference - Raw
—



T° dependence of BS



Line color =
Seawater °C

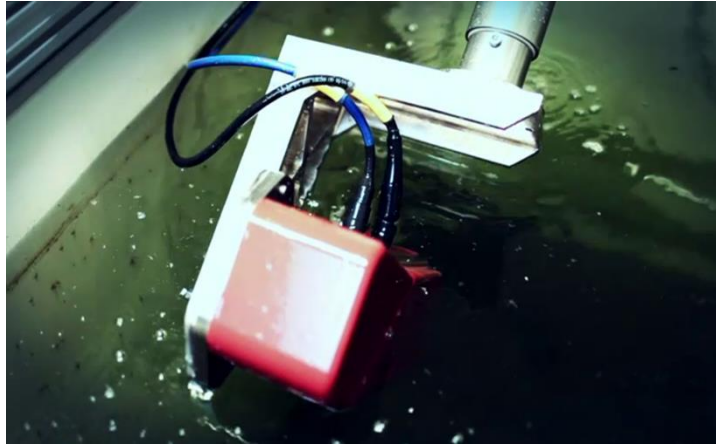


- BS angular response correlated with sea water temperature
- As high as 4.5 dB between “cold” and “warm” water

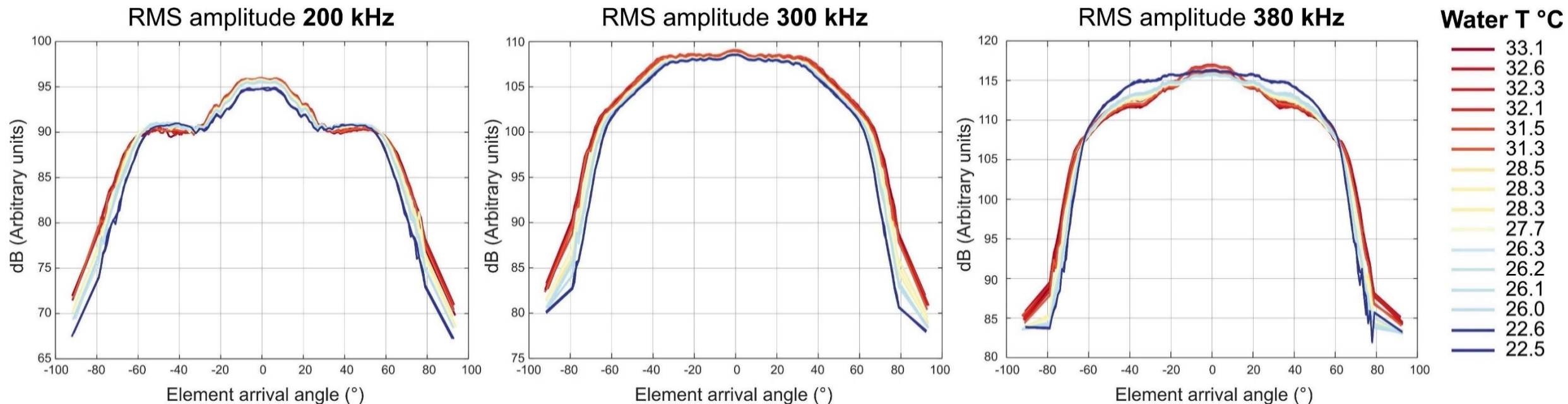
In-tank measurements confirm the T° dependence



Kongsberg Discovery



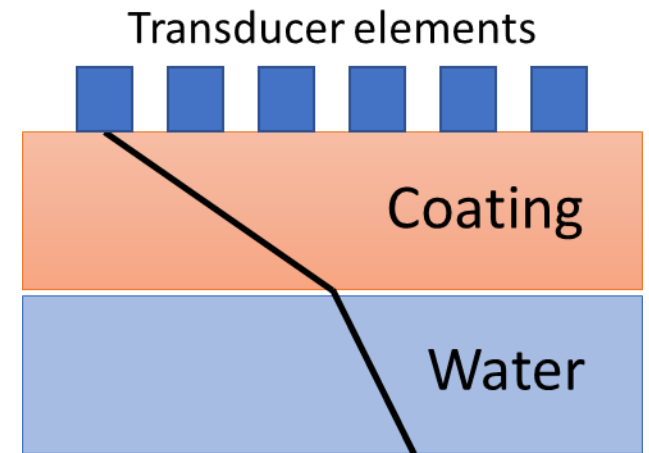
- With one of the earliest EM2040 RX units
- RX directivity change with $T^\circ\text{C}$
- Complex, changes with frequency



T° dependence causes? Hypotheses:

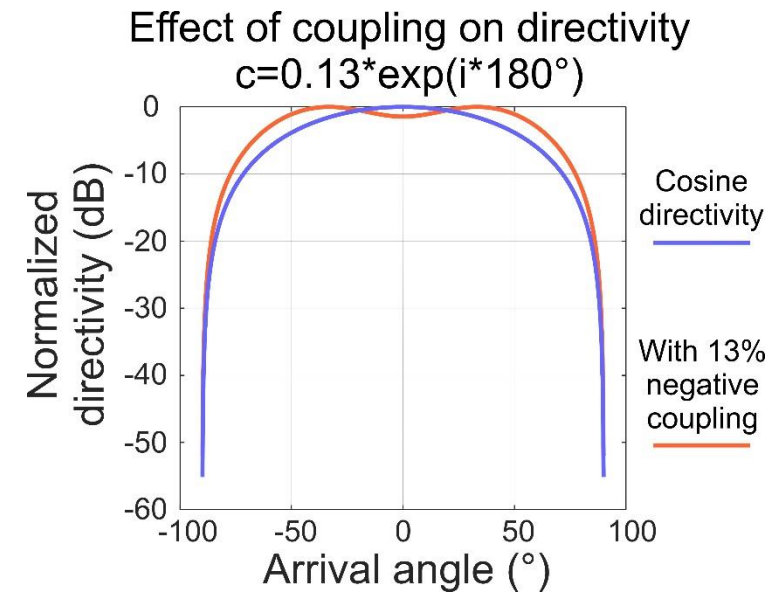
1. Snell law – Refraction

- Coating sound speed change with T°
- Leads to a change in refraction
- Not sufficiently taken into account?
- But should only cause a scaled directivity



2. Coupling

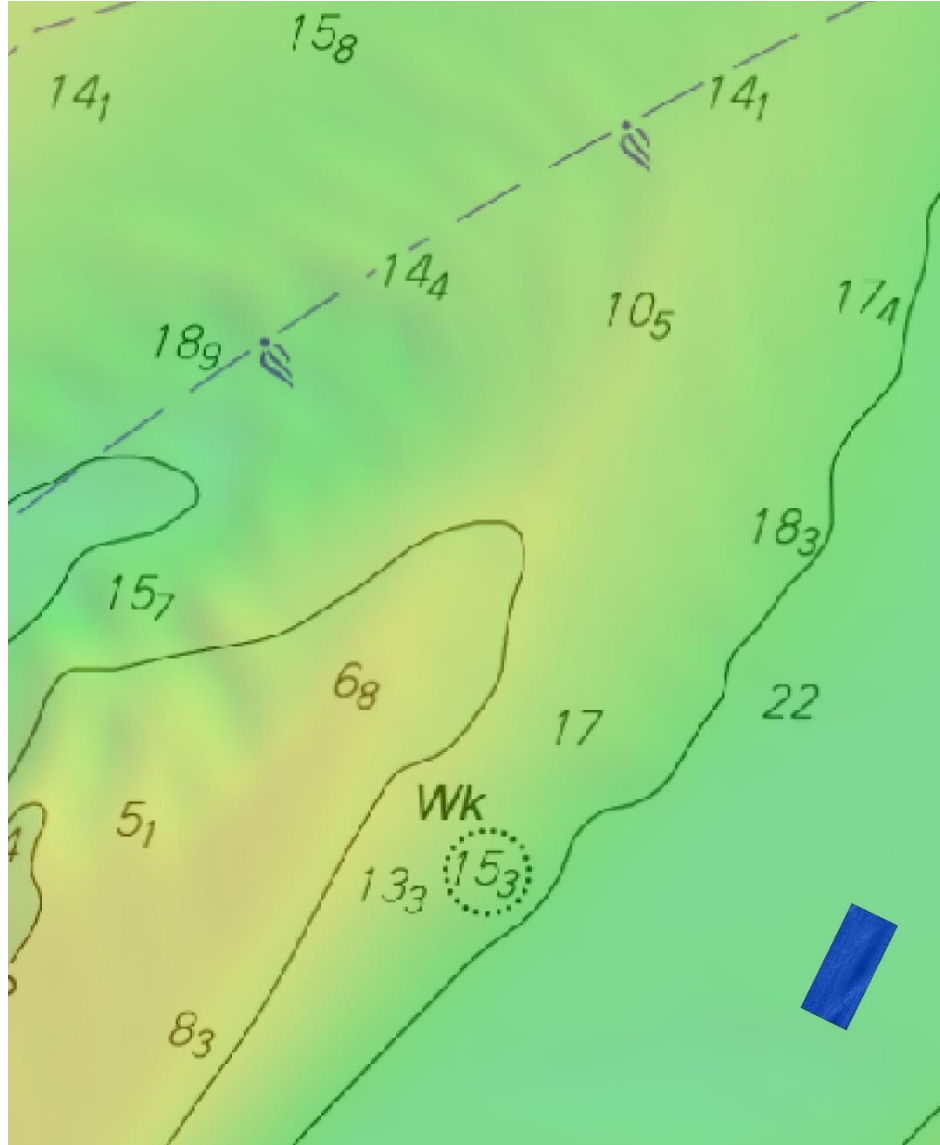
- Interaction between neighboring transducer elements
- Can produce various effects
- Complex relation to material parameters
- A probable cause of significant directivity variations
- Hard to model for real-time compensation



3. Other phenomena that can give non-symmetric effects must be considered

Solution: Survey of the Kwinte area always!

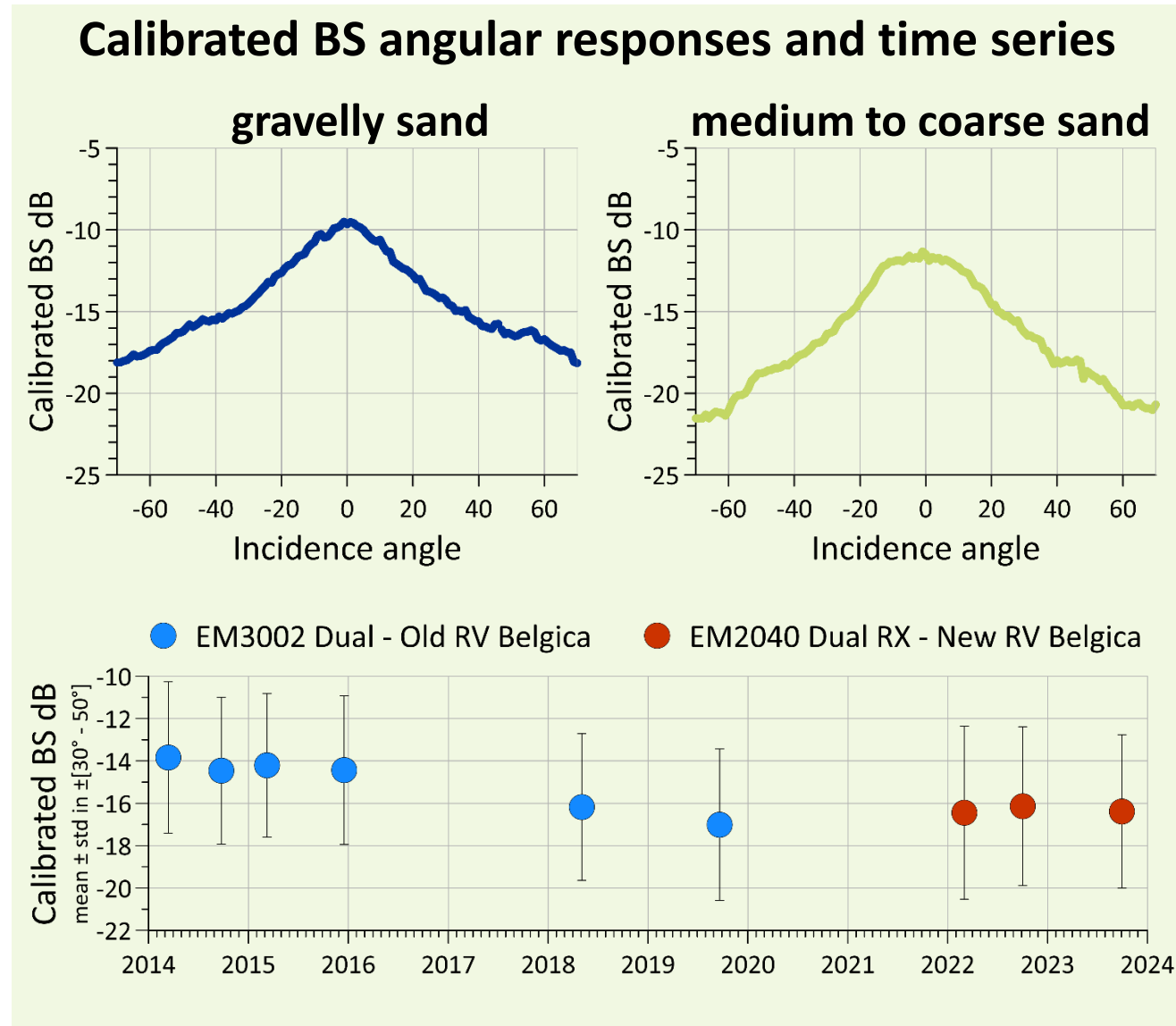
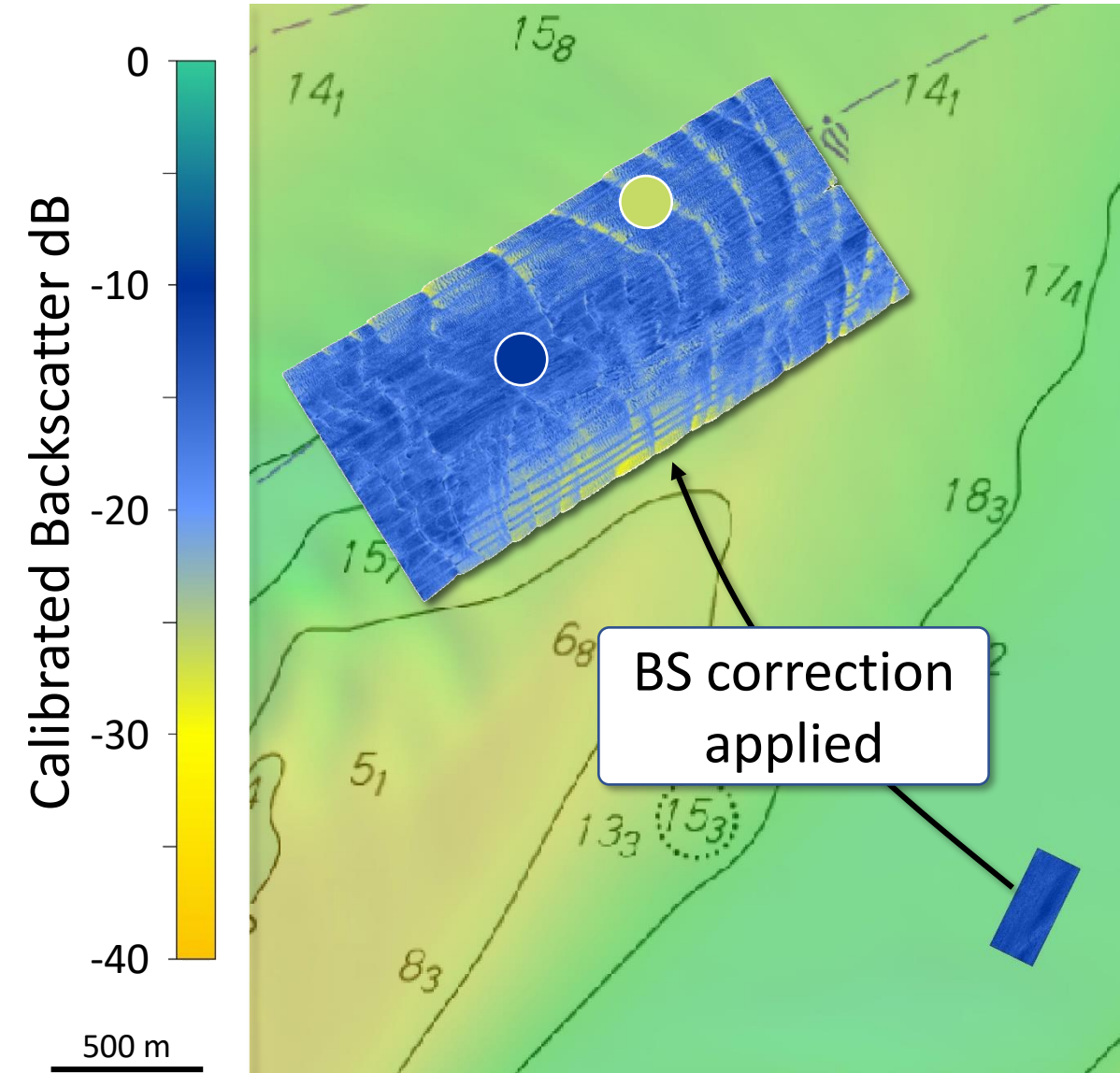
Using our usual monitoring mode (300 kHz, normal mode, medium pulse length)



500 m

Solution: Survey of the Kwinte area always!

- ☑ One calibration per measurement campaign applied to all data



Thank you!
Question?